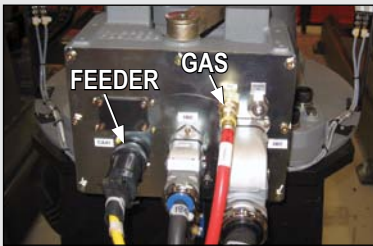




PATENTED ARM DESIGN



IMPROVED PART ACCESS



INTEGRATED UTILITIES

## TOP REASONS TO BUY

- Longest-reach arc welding robot with integrated torch cable
- Streamlined design improves torch access into tight spaces
- Patented multiple robot control allows more arms to be combined in workcell
- Extra-long arm reduces need for tracks



# MA3100

• ARC WELDING •

**Payload: 3 kg**

**Mounting Options: Ceiling/Wall (MA3100T)**

## “Master Arc” Welding Robot Extra-Long, Streamlined and Powerful

- Extended-reach MA3100 “Master Arc” welding robot provides longest reach in its class.
- Reduces welding cycle time due to cutting-edge Sigma-5 AC servo motor control technology and new ARM (Advanced Robot Motion) control.
- 3,121 mm (122.9”) reach;  $\pm 0.15$  mm ( $\pm 0.006$ ”) repeatability.
- Integrated through-the-arm torch cabling eliminates cable interference, simplifies programming and reduces cable wear.
- Feeder cable and welding utilities (gas and air hoses) can be routed through robot base to upper arm.
- Hollow upper arm maintains optimum bend radius of welding torch cable, maximizing weld performance. T-axis can rotate torch  $\pm 200$  degrees without cable interference.
- Arm design prevents bent, pinched or stretched cables regardless of torch orientation or part size or shape; minimizes wire feed problems and optimizes weld performance.
- Floor-mounted model is standard. Ceiling- or wall-mounted versions (MA3100T) available.

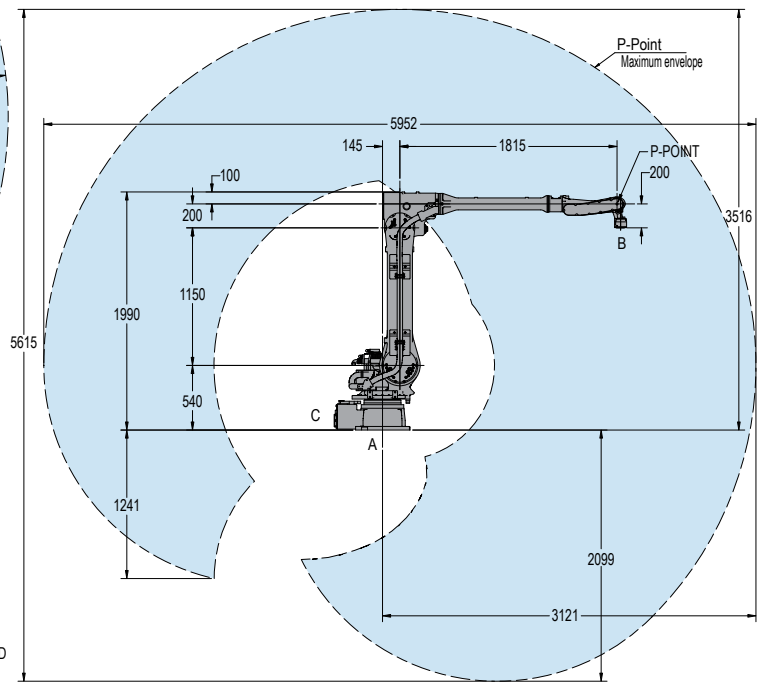
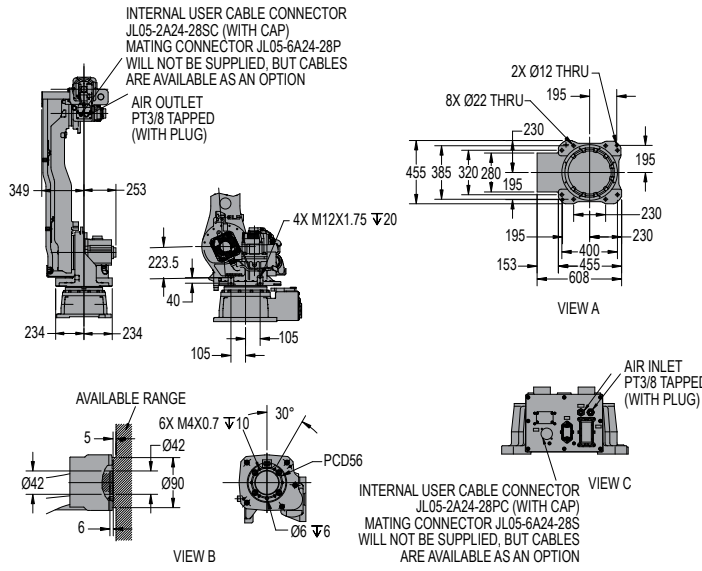
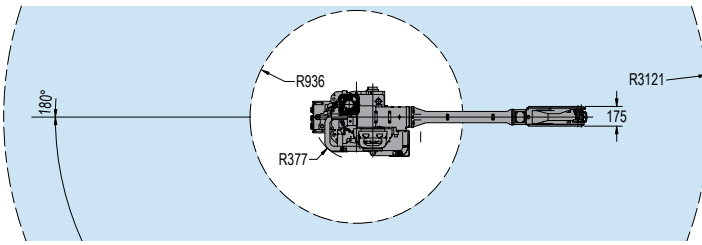
- Ideally suited for use in workcells with larger workpieces, as well as for applications that require access to parts in tight spots or those with potential interference from fixtures.
- Backed by industry’s first two-year torch cable warranty.

## DX100 Controller

- Patented multiple robot control supports up to 8 robots/72 axes.
- Windows® CE programming pendant with color touch screen and USB interface.
- DX100 welding full function arc welding software including graphics-based weld file settings.
- Faster processing speeds for smoother interpolation. Quicker I/O response. Accelerated Ethernet communication.
- Extensive I/O suite includes integral PLC and touch screen HMI, 2,048 I/O and graphical ladder editor.
- Supports all major fieldbus networks, including EtherNet/IP, DeviceNet, Profibus-DP and many others.
- Compliant to ANSI/RIA R15.06-1999 and other relevant ISO and CSA safety standards. Optional Category 3 functional safety unit.

# MA3100 ROBOT

All dimensions are metric (mm) and for reference only. Please request detail drawings for all design/engineering requirements.



MA3100 SPECIFICATIONS		
<b>Structure</b>	Vertical jointed-arm type	
<b>Controlled Axes</b>	6	
<b>Payload</b>	3 kg (6.6 lbs)	
<b>Vertical Reach</b>	5,615 mm (221.1")	
<b>Horizontal Reach</b>	3,121 mm (122.9")	
<b>Repeatability</b>	±0.15 mm (±0.006")	
<b>Maximum Motion Range</b>	S-Axis (Turning/Sweep) L-Axis (Lower Arm) U-Axis (Upper Arm) R-Axis (Wrist Roll) B-Axis (Bend/Pitch/Yaw) T-Axis (Wrist Twist)	±180° +135°/-90° +251°/-160° ±150° +180°/-45° ±200°
<b>Maximum Speed</b>	S-Axis L-Axis U-Axis R-Axis B-Axis T-Axis	180°/s 178°/s 178°/s 400°/s 410°/s 610°/s
<b>Approximate Mass</b>	501 kg (1,104.7 lbs)	
<b>Brakes</b>	All axes	
<b>Power Consumption</b>	1.5 kVA	
<b>Allowable Moment</b>	R-Axis B-Axis T-Axis	8.8 N • m 8.8 N • m 2.9 N • m
<b>Allowable Moment of Inertia</b>	R-Axis B-Axis T-Axis	0.27 kg • m <sup>2</sup> 0.27 kg • m <sup>2</sup> 0.03 kg • m <sup>2</sup>

DX100 CONTROLLER SPECIFICATIONS**	
<b>Dimensions (mm)</b>	800 (w) x 1,000 (h) x 650 (d) (31.5" x 39.4" x 25.6")
<b>Approximate Mass</b>	250 kg max. (551.3 lbs)
<b>Cooling System</b>	Indirect cooling
<b>Ambient Temperature</b>	During operation: 0° to 45° C (32° to 113° F) During transit and storage: -10° to 60° C (14° to 140° F)
<b>Relative Humidity</b>	90% max. non-condensing
<b>Primary Power Requirements</b>	3-phase, 240/480/575 VAC at 50/60 Hz
<b>Digital I/O</b>	Standard I/O: 40 inputs/40 outputs consisting of 16 system inputs/ 16 system outputs, 24 user inputs/24 user outputs 32 Transistor Outputs; 8 Relay Outputs Max. I/O (optional): 2,048 inputs and 2,048 outputs
<b>Position Feedback</b>	By absolute encoder
<b>Program Memory</b>	JOB: 200,000 steps, 10,000 instructions CIO Ladder Standard: 15,000 steps Expanded: 20,000 steps
<b>Pendant Dim. (mm)</b>	169 (w) x 314.5 (h) x 50 (d) (6.7" x 12.4" x 2")
<b>Pendant Weight</b>	.998 kg (2.2 lbs)
<b>Interface</b>	One Compact Flash slot; One USB port (1.1)
<b>Pendant Playback Buttons</b>	Teach/Play/Remote Keyswitch selector Servo On, Start, Hold, and Emergency Stop Buttons
<b>Programming Language</b>	INFORM III, menu-driven programming
<b>Maintenance Functions</b>	Displays troubleshooting for alarms, predicts reducer wear
<b>Number of Robots/Axes</b>	Up to 8 robots, 72 axes
<b>Multi Tasking</b>	Up to 16 concurrent jobs, 4 system jobs
<b>Fieldbus</b>	DeviceNet Master/Slave, AB RIO, Profibus, Interbus-S, M-Net, CC Link, EtherNet IP/Slave
<b>Ethernet</b>	10 Base T/100 Base TX
<b>Safety</b>	Dual-channel Emergency Stop Pushbuttons, 3-position Enable Switch, Manual Brake Release Meets ANSI/RIA R15.06-1999, ANSI/RIA/ISO 10218-1-2007 and CSA Z434-03

\*\*See DX100 Controller data sheet (DS-399) for complete specifications