COMPLETE OUR ONLINE SURVEY

Motoman is committed to total customer satisfaction! Please give us your feedback on the technical manuals you received with your Motoman robotic solution.

To participate, go to the following website:

http://www.motoman.com/forms/techpubs.asp
# Table of Contents

## Chapter 1
**Introduction** ................................................................. 1
  1.1 About This Document .................................................. 1
  1.2 System Overview ....................................................... 2
  1.2.1 System Layout ..................................................... 2
  1.2.2 Major Components ................................................ 3
  1.2.3 Optional Equipment ................................................ 3
  Reference to Other Documentation ....................................... 3
  Customer Service Information .......................................... 4

## Chapter 2
**Safety** .............................................................................. 5
  2.1 Introduction .............................................................. 5
  2.2 Important Advisory Information ..................................... 6
  2.3 General Safeguarding Tips ............................................ 6
  2.4 Mechanical Safety Devices .......................................... 7
  2.5 Installation Safety ...................................................... 7
  2.6 Programming, Operation, and Maintenance Safety .......... 8

## Chapter 3
**Equipment Description** .................................................... 11
  3.1 Robot Description ...................................................... 11
  3.2 NX100 Controller ....................................................... 11
  3.2.1 Programming Pendant ............................................ 12
  3.3 Operator Station ....................................................... 16
  3.4 Weld Station - MHT-150 Positioner .............................. 17
  3.5 Welding Equipment .................................................... 17
  3.5.1 Wire Feeder .......................................................... 17
  3.5.2 GMAW Torch ........................................................ 17
  3.5.3 Power Sources ...................................................... 17
  3.6 Safety Features .......................................................... 19
  3.6.1 Arc Screens .......................................................... 19
  3.6.2 Fencing ............................................................... 19
  3.6.3 Safety Light Curtains ............................................. 19
  3.6.4 Emergency Stops (E-STOPS) ................................... 19
  3.6.5 ENABLE Switch .................................................... 20
  3.6.6 Brake Release ...................................................... 20
  3.6.7 Interlocked Cell Door ............................................ 20
## Chapter 4
### Installation

- Materials Required .................................................................................................................. 21
  - Customer-Supplied Items .................................................................................................... 21
  - List of Tools ...................................................................................................................... 21
- Site Preparation ..................................................................................................................... 22
- Installing the Stations ............................................................................................................ 22
- Installing the Robot .............................................................................................................. 25
  - Removing the Robot Shipping Bracket ........................................................................... 25
  - Removing the Barrier Station Shipping Bolts ................................................................. 26
- Installing the Fencing ............................................................................................................ 27
- Installing the Arc Curtains .................................................................................................... 28
- Installing the Safety Light Curtains ..................................................................................... 28
  - Installation ...................................................................................................................... 28
  - Alignment ......................................................................................................................... 28
- Installing the Auxiliary Equipment ....................................................................................... 29
- Connecting the Cables .......................................................................................................... 29
  - Connecting the Earth Ground ......................................................................................... 29
  - Connecting the Robot Cables ......................................................................................... 30
- Connecting the Power .......................................................................................................... 30
- Conducting a Safety/Operation Check .................................................................................. 31
- Installation of Tooling and Fixtures ....................................................................................... 31

## Chapter 5
### Operation

- Programming ......................................................................................................................... 33
- Daily Operation .................................................................................................................... 34
  - Start-Up ........................................................................................................................... 34
  - Robot Home Position ....................................................................................................... 34
  - Start the Master Job ......................................................................................................... 35
  - Perform Operation Cycle ................................................................................................. 35
    - Re-entering Station after Cycle Latch ............................................................................ 36
  - Shutdown ......................................................................................................................... 36
- System Recovery .................................................................................................................. 37
  - Alarms and Errors ............................................................................................................ 37
    - Error Messages ............................................................................................................. 37
    - Minor Alarms ................................................................................................................ 37
    - Major Alarms ................................................................................................................ 37
  - E-STOP .............................................................................................................................. 37
  - Shock Sensor Recovery .................................................................................................... 38
  - Brake Release .................................................................................................................. 38
Chapter 1
Introduction

The ArcWorld II-500 system is part of the ArcWorld family of standardized arc welding solutions. It is a fully integrated welding system, and is supported from wire to weld by Motoman, Inc.

1.1 About This Document

This manual is intended as an introduction and overview for personnel who have received operator training from Motoman, and who are familiar with the operation of their Motoman robot model. For more detailed information, refer to the manuals listed in Section 1.3. This manual contains the following chapters:

CHAPTER 1 — INTRODUCTION
This section provides general information about the ArcWorld II-500 and its components, a list of reference documents, and customer service information.

CHAPTER 2 — SAFETY
This section provides information regarding the safe use and operation of the ArcWorld II-500 system.

CHAPTER 3 — DESCRIPTION OF EQUIPMENT
This section provides a detailed description of the major components of the ArcWorld II-500 system. This section also includes a table of component specifications.

CHAPTER 4 — INSTALLATION
This section provides instructions for set up and installation of the ArcWorld II-500 system.

CHAPTER 5 — OPERATION
This section provides instructions for basic operation of the ArcWorld II-500 system. This section also provides procedures for start-up, loading, normal operation, fault recovery, and shutdown. Sample robot programs are also included in this section.

CHAPTER 6 — MAINTENANCE
This section contains a table listing periodic maintenance requirements for the components of the ArcWorld II-500 cell.
1.2 System Overview

Motoman’s ArcWorld II-500 robotic solutions are high-performance, pre-engineered workcells that are ideal for small to medium part fabrication at medium to high volumes. Fully integrated ArcWorld II-500 series workcells feature two MH150 rotary positioner modules, a high-performance EA1400N Motoman robot with NX100 controller, and a completely integrated welding package. The cell provides a full complement of safety features designed to protect both personnel and equipment.

Figure 1 illustrates the system layout of the ArcWorld II-500 cell.

![Figure 1 System Layout](image)

Note: This manual is for a standard Motoman system. If your system is a custom or modified system, please use the drawing and Bill of Material (BOM) provided with the system for troubleshooting and spares provisioning.

1.2.1 System Layout

All ArcWorld II-500 components are lagged directly to the floor. A spanner plate is used to help maintain proper alignment between the robot and positioner modules. However, optional mounting bases are available for both the robot/positioner modules and controller. The robotic cell is fully enclosed by safety fencing and an interlocking door. The interlocking operator doors allow the operator to load parts at one station while the robot is welding at the other station. Light
curtains provide a safety zone to prevent the robot from entering an occupied station. All operator controls, including those on the NX100 controller and welding power supply, are accessible from outside the robotic enclosure.

1.2.2 Major Components

The ArcWorld II-500 includes the following major components:

- Motoman EA1400N manipulator and NX100 controller
- Two work stations featuring MHT-150 headstock/tailstock drive assemblies
- Common operator station
- Welding equipment, including the following:
  - Welding power source
  - Motoman torch (water-cooled or air-cooled)
  - Wire feeder
  - Applicable welding interface
  - Torch mount
- Safety equipment, including the following:
  - Safety fencing with arc curtains
  - Interlocked light curtains
  - Interlocked cell door
  - Interlocked station doors

1.2.3 Optional Equipment

The following optional equipment is available for use with the ArcWorld II-500:

- Torch tender
- Wire cutter
- Water circulator
- Common base for robot, positioners and fencing
- Common base for controller and welding power source

1.3 Reference to Other Documentation

For additional information refer to the following:

- Motoman EA1400N Manipulator Manual (P/N 149209-1)
- Motoman NX100 Controller Manual (P/N 149201-1)
• Motoman Operator's Manual for Arc Welding (P/N 149235-1)
• Motoman Concurrent I/O Parameter Manual (P/N 149230-1)
• Motoman MH-150 Positioner Manual (PN 146703-1)
• Vendor manuals for system components not manufactured by Motoman

1.4 Customer Service Information

If you are in need of technical assistance, contact the Motoman service staff at (937) 847-3200. Please have the following information ready before you call:

• Robot Type (EA1400N)
• Application Type (arc welding)
• System Type (ArcWorld II-500)
• Software Version (access using MAIN MENU, SYSTEM INFO, VERSION on programming pendant)
• Robot Serial Number (located on back side of robot arm)
• Robot Sales Order Number (located on front door of NX100 controller)
Chapter 2
Safety

2.1 Introduction

It is the purchaser’s responsibility to ensure that all local, county, state, and national codes, regulations, rules, or laws relating to safety and safe operating conditions for each installation are met and followed.

We suggest that you obtain and review a copy of the ANSI/RIA National Safety Standard for Industrial Robots and Robot Systems (ANSI/RIA R15.06-1999). You can obtain this document from the Robotic Industries Association (RIA) at the following address:

Robotic Industries Association
900 Victors Way
P.O. Box 3724
Ann Arbor, Michigan 48106
TEL: (734) 994-6088
FAX: (734) 994-3338
http://www.roboticsonline.com

Ultimately, well-trained personnel are the best safeguard against accidents and damage that can result from improper operation of the robot system. The customer is responsible for providing adequately trained personnel to operate, program, and maintain the robot cell. NEVER ALLOW UNTRAINED PERSONNEL TO OPERATE, PROGRAM, OR REPAIR THE ROBOT SYSTEM!

We recommend approved Motoman training courses for all personnel involved with the operation, programming, or repair of the robot system. This training is designed to familiarize personnel with the safe and correct operation of the robot system.
This safety section addresses the following:

- Standard Conventions (Section 2.2)
- General Safeguarding Tips (Section 2.3)
- Mechanical Safety Devices (Section 2.4)
- Installation Safety (Section 2.5)
- Programming, Operation, and Maintenance Safety (Section 2.6)

### 2.2 Important Advisory Information

Throughout this manual you will find advisory paragraphs (denoted by graphic symbols and bold typeface). All of these (except "NOTE") direct the reader's attention to information and procedures that are essential to the safety of personnel or protection of equipment.

The type of information contained in the various advisories is described below. These are listed here in descending order of importance to the safety of personnel and protection of equipment.

#### DANGER!

Information appearing under the DANGER caption concerns the protection of personnel from an immediate and imminent hazards that, if not avoided, will result in immediate, serious personal injury or loss of life in addition to equipment damage.

#### WARNING!

Information appearing under the WARNING caption concerns the protection of personnel and equipment from potential hazards that can result in personal injury or loss of life in addition to equipment damage.

#### CAUTION!

Information appearing under the CAUTION caption concerns the protection of personnel and equipment, software, and data from hazards that can result in minor personal injury or equipment damage.

Note: Information appearing in a Note caption provides additional information that can be helpful in understanding the item being explained.

### 2.3 General Safeguarding Tips

All operators, programmers, plant and tooling engineers, maintenance personnel, supervisors, and anyone working near the robot must become familiar with the operation of this equipment. All personnel involved with the operation of the equipment must understand potential dangers of operation. General safeguarding tips are as follows:

- Improper operation can result in personal injury and/or damage to the equipment. Only trained personnel familiar with the operation of this robot, the operator's manuals, the system equipment, and options and accessories should be permitted to operate this robot system.
• Do not enter the robot cell while it is in automatic operation. Programmers must have the teach pendant when they enter the robot cell.

• Improper connections can damage the robot. All connections must be made within the standard voltage and current ratings of the robot I/O (Inputs and Outputs).

• The robot must be placed in Emergency Stop (E-STOP) mode whenever it is not in use.

• In accordance with ANSI/RIA R15.06-1999, section 4.2.5, Sources of Energy, use lockout/tagout procedures during equipment maintenance. Refer also to Section 1910.147 (29CFR, Part 1910), Occupational Safety and Health Standards for General Industry (OSHA).

2.4 Mechanical Safety Devices

The safe operation of the robot, positioner, auxiliary equipment, and system is ultimately the user's responsibility. The conditions under which the equipment will be operated safely should be reviewed by the user. The user must be aware of the various national codes, ANSI/RIA R15.06-1999 safety standards, and other local codes that may pertain to the installation and use of industrial equipment. Additional safety measures for personnel and equipment may be required depending on system installation, operation, and/or location. The following safety equipment is provided as standard:

• Safety fences and barriers
• Light curtains and/or safety mats
• Door interlocks
• Emergency stop palm buttons located on operator station, robot controller, and programming pendant

Check all safety equipment frequently for proper operation. Repair or replace any non-functioning safety equipment immediately.

2.5 Installation Safety

Safe installation is essential for protection of people and equipment. The following suggestions are intended to supplement, but not replace, existing federal, local, and state laws and regulations. Additional safety measures for personnel and equipment may be required depending on system installation, operation, and/or location. Installation tips are as follows:

• Be sure that only qualified personnel familiar with national codes, local codes, and ANSI/RIA R15.06-1999 safety standards are permitted to install the equipment.
• Identify the work envelope of each robot with floor markings, signs, and barriers.
• Position all controllers outside the robot work envelope.
• Whenever possible, install safety fences to protect against unauthorized entry into the work envelope.
• Eliminate areas where personnel might get trapped between a moving robot and other equipment (pinch points).
• Provide sufficient room inside the workcell to permit safe teaching and maintenance procedures.

2.6 Programming, Operation, and Maintenance Safety

All operators, programmers, plant and tooling engineers, maintenance personnel, supervisors, and anyone working near the robot must become familiar with the operation of this equipment. Improper operation can result in personal injury and/or damage to the equipment. Only trained personnel familiar with the operation, manuals, electrical design, and equipment interconnections of this robot should be permitted to program, operate, and maintain the system. All personnel involved with the operation of the equipment must understand potential dangers of operation.

• Inspect the robot and work envelope to be sure no potentially hazardous conditions exist. Be sure the area is clean and free of water, oil, debris, etc.
• Be sure that all safeguards are in place. Check all safety equipment for proper operation. Repair or replace any non-functioning safety equipment immediately.
• Do not enter the robot cell while it is in automatic operation. Be sure that only the person holding the programming pendant enters the workcell.
• Check the E-STOP button on the programming pendant for proper operation before programming. The robot must be placed in Emergency Stop (E-STOP) mode whenever it is not in use.
• Back up all programs and jobs onto suitable media before program changes are made. To avoid loss of information, programs, or jobs, a backup must always be made before any service procedures are done and before any changes are made to options, accessories, or equipment.
• Any modifications to PART 1, System Section, of the robot controller concurrent I/O program can cause severe personal injury or death, as well as damage to the robot! Do not make any modifications to PART 1, System Section. Making any changes without the written permission of Motoman will VOID YOUR WARRANTY!
• Some operations require standard passwords and some require special passwords. Special passwords are for Motoman use only. YOUR WARRANTY WILL BE VOID if you use these special passwords.
• The robot controller allows modifications of PART 2, User Section, of the concurrent I/O program and modifications to controller parameters for maximum robot performance. Great care must be taken when making these modifications. All modifications made to the controller will change the way the robot operates and can cause severe personal injury or death, as well as damage the robot and other parts of the system. Double-check all modifications under every mode of robot operation to ensure that you have not created hazards or dangerous situations.
• Check and test any new or modified program at low speed for at least one full cycle.
• This equipment has multiple sources of electrical supply. Electrical interconnections are made between the controller and other equipment. Disconnect and lockout/tagout all electrical circuits before making any modifications or connections.

• Do not perform any maintenance procedures before reading and understanding the proper procedures in the appropriate manual.

• Use proper replacement parts.

• Improper connections can damage the robot. All connections must be made within the standard voltage and current ratings of the robot I/O (Inputs and Outputs).
Chapter 3

Equipment Description

3.1 Robot Description

The Motoman six-axis EA1400N “Expert Arc” robot is specifically designed for arc welding applications. The EA1400N has a payload of 3 kg (6.6 lbs.) and features a horizontal reach of 1388-mm (54.6 inch) and a relative positioning accuracy of ±0.08 mm (±0.003 inch). The EA-series robots have a patented internal cabling design that provides high flexibility and streamlines the robot profile, allowing access into confined spaces. The robot’s B-axis features an expanded range of motion which improves circumferential welding on cylindrical work pieces. The T-axis can rotate the torch ±360 degrees without cable interference.

The robot can be mounted on the floor, wall, or ceiling with minor modifications. The S-axis has been restricted by hardstops for use in this system. For more information, refer to the manipulator manual that came with your system.

3.2 NX100 Controller

The NX100 robotic controller, shown in Figure 2, features a Windows® CE programming pendant with color touch screen, high-speed processing, built-in Ethernet, and a robust PC architecture. The NX100 easily handles multiple tasks and can control up to four robots (up to 36 axes, including robots and external axes), and I/O devices. Advanced Robot Motion (ARM) control provides high-performance path accuracy and vibration control.

The NX100 coordinates the operation of the ArcWorld II-500 system. It controls manipulator movement and welding power supply, processes input and output signals, and provides the signals to operate the welding system. It maintains variable data and performs numeric processing to convert to and from different coordinate systems. In addition, the controller provides main logic functions, servo control, program and constant data memory, and power distribution. For more information, refer to the controller manual that came with your system.
3.2.1 Programming Pendant

The programming pendant (see Figure 3) is the primary user interface for the system and features a cross-shaped navigation cursor that reduces teaching time by 30 percent. The pendant has a 6.5-inch full color touch screen display (640 x 480 VGA) and provides a convenient Compact Flash slot for easy memory back-ups. The system uses the INFORM III robot language and a menu-driven interface to simplify operator interaction with the robot.

Most operator controls are located on the pendant, allowing the control cabinet to be mounted remotely. An optional on-line troubleshooting guide for expert system maintenance is also available on the pendant. By using the pendant, the operator can teach robot motion, and perform programming, editing, maintenance, and diagnostic functions. For more information, refer to the operator’s manual that came with your system.

Note: The programming pendant display goes into screen saver mode after a few minutes of inactivity. Press any key to restore screen.
Figure 3 Programming Pendant

Mode Selector Switch
The Mode Selector Switch allows the operator to select Remote, Play or Teach mode. In Remote mode, control of the system is transferred to the operator station. When Play or Teach is selected, the programming pendant controls system operation. When Play mode is selected on the programming pendant, the operator must also press the PLAY ENABLE button on the controller door to initiate Play mode.

Menu Area
The Menu Area contains menu selections for the currently selected screen.

General Purpose Display Area
The General Purpose Display Area displays the currently selected menu choice.

Emergency Stop (E-STOP)
Pressing the E-STOP button puts the controller in Emergency Stop and stops all system operation.
**Keypad**
The user keypad on the programming pendant serves as an input device. The keys are grouped into different functional sections to simplify operator use.

**Status Area**
The Status Area shows system status via the following symbols:

- Active Robot, External Axis, or Base Axis
- R1, R2, R3; S1, S2, etc.; or B1, B2, etc.
- Coordinate System
- Joint, World, Cylindrical, Tool, or User Frame
- Manual Speed Setting
- Inching, Low, Medium, or High
- Cycle Mode
- Step, 1-Cycle, or Auto
- System Status
- E-Stop, Stop, Running/Start, Hold, or Alarm
- Additional Pages (when applicable)

**MAIN MENU Key**
The MAIN MENU key returns the pendant display to the initial start-up menu. Use the cursor key or the touch screen to choose from the following menu options:

- **JOB**
  This option accesses job selections including: Master Job, Select Job, Job Capacity, and Create New Job while in TEACH mode.

- **ARC WELDING, GENERAL, HANDLING, and SPOT WELDING**
  This option allows you to select the applications available to the controller.

- **VARIABLE**
  This option accesses the display and editing menu for the arithmetic variables and display of position variables.

- **IN/OUT**
  This option accesses DETAIL and SIMPLE displays of all XRC I/O signals. In EDITING or MAINT. mode, Universal Outputs can be forced ON or OFF.

- **ROBOT**
  This option accesses robot information including: CURR.POS, POWER ON/OFF, POS, COMMAND POS, SECOND HOME POS, OPE. ORIGIN POS, and TOOL and USER COORDINATE.

- **SYSTEM INFO**
  This option provides Version information for both hardware and software, Alarm History, and Monitoring Time.

- **FD/CF**
  This option accesses menu choices for FD (floppy disk) or CF (compact flash) program backup.
• SETUP
  This allows the user to set up system conditions and assign hot keys.

AREA Key
The Area key moves the cursor to the different areas of the display screen.

CURSOR Key
The Cursor key is an 8-way, directional key that moves the up, down, left or right to highlight a desired item that can then be chosen using the SELECT key.

SELECT Key
The SELECT key is used to choose the item currently highlighted by the cursor.

FLASH MEMORY Slot
The compact FLASH MEMORY card slot allows for easy memory backups.

ENABLE Switch
The ENABLE switch (see Figure 4) is a three-position switch located on the left rear of the programming pendant. It is a safety feature that controls servo power while in TEACH mode. When pressed in, this switch enables servo power to be turned on. However, should the operator release the switch, or grasp it too tightly, servo power is immediately removed, preventing further robot movement.

SERVO ON Key
When the pendant is in TEACH mode, The SERVO ON key turns servo power ON when the ENABLE: switch is activated. When the pendant is in PLAY mode, the SERVO ON key turns servo power on.

Figure 4 Enable Switch
3.3 Operator Station

The operator station (see Figure 5) includes a NEMA enclosure that is fence mounted. The following paragraphs describe the operator station controls.

![Operator Station Diagram](image)

**Figure 5 Operator Station**

**Cycle Start/Cycle Latched**

The operation of the CYCLE START/CYCLE LATCHED button is dependent on the structure of the Master job. Altering the Master job could result in injury to personnel or damage to the equipment. The CYCLE START/CYCLE LATCHED button initiates a job cycle if the robot is in the Home position. In Auto mode, the station door closes and the robot moves to the station to begin work. If the CYCLE START button is pressed while the robot is outside Home position, the CYCLE START command does not execute until the robot returns to Home position.

The CYCLE LATCHED lamp illuminates when the CYCLE START button is pressed while the robot is outside Home position, the CYCLE START command does not execute until the robot returns to Home position.

**Positioner Auto/Manual**

The POSITIONER AUTO/MANUAL selector switch changes the function of the CYCLE START button.

- In AUTOMATIC mode, pressing the CYCLE START button closes the station door and starts the job cycle. The door typically opens at the end of the job cycle.
- In MANUAL mode, pressing the CYCLE START button opens or closes a station door on demand. If the door is in motion, pressing the CYCLE START button changes its direction. MANUAL mode can be used to reopen the station door when part adjustments are required after CYCLE START has been pressed and the operator door has closed.

**Emergency Stop (E-STOP)**

Pressing an E-STOP button removes servo power and stops all system operation. Brakes are applied to the robot and all positioner motion is stopped.
3.4 **Weld Station - MHT-150 Positioner**

The ArcWorld II-500 features two weld stations with MHT-150 positioners, each with a door that protects the operator from arc radiation, weld splatter, and physical contact with the robot arm. When the robot is finished working, the door lowers, giving the operator access to unload and reload parts from the fixture. When the door is open, the in-position switches on the headstock must actuate or the system will E-stop.

For specifications on the MHT-150 positioner see Motoman P/N 146703-1, MH-Series Positioner with MotoMount. For detailed specifications including parts lists breakdown for the barrier assembly, refer to the Barrier Assembly Manual, P/N 147500-1.

3.5 **Welding Equipment**

In its standard configuration, the ArcWorld system includes a welding power source, wire feeder, torch, and torch mount. Optional equipment - including water circulators, Com-Arc units, and torch tenders - may also be included with your system.

3.5.1 **Wire Feeder**

The wire feeder mounts on the robot arm. This 4-roll wire feeder provides reliable wire feeding at rates up to 750 inches per minute (ipm). An integral gas valve provides fast gas response time. Interchangeable feed rolls are used to accommodate different types and sizes of wire.

3.5.2 **GMAW Torch**

The ArcWorld system uses either an air-cooled or a water-cooled robotic/automatic GMAW torch. These are heavy-duty torches designed for quick replacement and minimum robot reprogramming. The GMAW torch is installed at the end of the robot wrist. For applications that use the water-cooled torch, the ArcWorld system includes a water circulator kit.

3.5.3 **Power Sources**

Motoman offers several different power sources for use with the ArcWorld II-500 system, depending on the system’s application. Figure 6 shows some of the more common power sources used. However, the power source your system uses may be different. For more specific information, refer to the vendor manual that came with your system.
Figure 6 Available Power Sources
3.6 Safety Features

The ArcWorld system includes a total safety environment. When all standard safety precautions are taken, the safety equipment helps to ensure safe operation of the robotic cell. The ANSI/RIA R15.06-1999 Robot Safety Standard stipulates the user is responsible for safeguarding.

Note: Users are responsible for determining whether the provided safeguards are adequate for plant conditions. Users must also ensure that safeguards are maintained in working order.

3.6.1 Arc Screens

**WARNING!**

Although the arc curtain blocks dangerous arc radiation, never look directly at the arc without protective eye wear!

Two arc screens are used on the ArcWorld system. The first is the arc screen door used on each station. This screen blocks arc radiation and sparks from the welding operation.

The material used to cover the safety fencing of the entire robotic cell acts as the second arc screen. This material reduces the amount of ultra-violet radiation that escapes from the robotic cell.

3.6.2 Fencing

The safety fencing provided with the ArcWorld system encloses the entire robotic cell. It forms a physical barrier preventing entry into the robot cell during automatic operation.

3.6.3 Safety Light Curtains

The light curtains monitor the position of the robot. As the robot moves from Station 1 to Station 2, a signal is sent out to the controller informing it of the robot penetrating the light curtain. This output and a signal from the operator door are interlocked with the “OK TO WORK” output, preventing the robot from welding when the operator door is open.

3.6.4 Emergency Stops (E-STOPS)

In addition to the safety features described above, the ArcWorld II-500 has strategically placed E-STOPS. These are operator-actuated devices that, when activated, immediately stop all system operation. Brakes are applied to the robot and all servo power is removed from the system. The following is a list of E-STOP locations:

- The controller door
- The programming pendant
- The operator station
3.6.5 ENABLE Switch

The ENABLE switch is a safety feature which controls servo power while in TEACH mode. When pressed in, this switch allows the operator to turn servo power ON. However, should the operator release the switch or grasp it too tightly, servo power is immediately removed, preventing further robot movement. For detailed information about the operation of the ENABLE switch, refer to the controller manual that came with your system.

3.6.6 Brake Release

The robot brakes are designed to protect the robot and other system components from damage in event of a system or robot failure. The brake release is a safety feature that allows the operator to release the brake of a specific robot axis when drive power has been removed from the system. Use the programming pendant to access the brake release function. Refer to paragraph 5.3.4 for brake release procedures.

3.6.7 Interlocked Cell Door

A safety interlock on the cell entrance door prevents entry into the cell during PLAY mode. If the cell door is opened when the robot is in PLAY mode, brakes are applied to the robot, all servo power is removed from the system, and all positioner motion is stopped.
Chapter 4

Installation

The ArcWorld II-500 system can be installed easily in just a short amount of time. Follow established safety procedures at all times throughout the installation process. Failure to use safe work practices can result in damage to the equipment and injury to the workers.

⚠️ CAUTION!
Installation of the ArcWorld system is not a task for the novice. The ArcWorld system is not fragile, but it is a highly sophisticated robotic system. Handle components with care. Rough handling can damage system electronic components.

4.1 Materials Required

All hardware necessary for installing the ArcWorld II-500 is included with the system. This section identifies customer-supplied items and tools required to complete installation.

4.1.1 Customer-Supplied Items

- Gas supply for the welding torches
- Three-phase power
- Earth ground cables with two earth ground stakes
- Weld wire
- Incoming air supply: 0.04cmm at 620.5 kPa (1.5scfm at 90 psi) for torch tender or wire cutter
- Stepladder
- Forklift and/or overhead crane

4.1.2 List of Tools

- Safety glasses
- Face shields
- Gloves
- Level
- Ratchet with 3/4-inch socket
- Adjustable wrench set
- Hammer drill with appropriate concrete bits
- Phillips and flat screwdrivers
- Hammer
- Socket set
- Forklift and/or overhead crane
- Air-impact gun with 3/4-inch socket
- Open-end wrench set
- Two socket-heads (Allen)
- Wrench sets (standard and metric)
4.2 Site Preparation

To prepare your site, proceed as follows:

1. Clear floor space needed for unit (see Figure 7).

   Note: To make installation easier, allow an additional 1.2 to 1.5 m (4 to 5 ft) on all sides of cell.

![Figure 7 Area Needed for Installation](image)

2. Gather all customer-supplied items and required tools listed in Section 4.1.

4.3 Installing the Stations

**WARNING!**
The barrier stations weigh 2000 kg (4400 lbs), make sure the lifting device used to move these objects are capable of safely handling this much weight.

1. Place the barrier stations side-by-side with the doors defining the front of the cell.
2. Fasten both barrier stations together using the spanner plate. Recheck the location of the barrier stations and adjust as necessary.
Figure 8 Spanner Plate

3. Place the robot at the other end of the spanner plate and fasten them together. Recheck the location of the barrier stations/robot module and adjust as necessary.

4. Attach the guards on the outside of each barrier station.

5. Attach the center guard - with operator station - between barrier stations.
Figure 9  Center Guard

6. Bolt the light curtain stand to the spanner and install the center barrier between the center guard and light curtain stand.

Figure 10  Center Guard
4.4 Installing the Robot

**WARNING!**
The robot/riser weighs approximately 450 kg (1000 lbs). Be sure your crane or forklift is capable of handling this much weight or damage to the equipment or injury to personnel can result.

2. Inspect robot, torch, and riser for shipping damage.

*Note: If damage is found, notify shipper immediately.*

3. Place robot riser in position behind spanner.

![Diagram](image)

**Figure 11** Robot Riser

4. Bolt robot riser to spanner.
5. Once components are correctly installed, anchor each component securely in place (refer to Appendix A for anchor requirements).

4.4.1 Removing the Robot Shipping Bracket

**CAUTION!**
Failure to remove shipping brackets from robot before operating the ArcWorld II-500 may result in damage to the robot drive mechanisms.

A yellow bracket (see Figure 12) prevents the robot from moving during shipping. The bracket secures the lower arm assembly to the S-axis housing. After the robot is in place, remove the shipping bracket.
4.4.2 Removing the Barrier Station Shipping Bolts

**CAUTION!**
Failure to remove the barrier station shipping bolts before operating the ArcWorld II-500 will result in a blown fuse and possible damage to equipment.

For shipping purposes, a yellow-capped shipping bolt is inserted through both front posts of each barrier station (four bolts total), and fastened to the counterbalance. Each bolt secures the counterbalance and the rest of the chain assembly to prevent the door from opening. These four bolts must be remove before operating the cell.
4.5 Installing the Fencing

The safety fencing is shipped in a separate crate along with all necessary hardware and specific assembly instructions. To install the safety fencing, proceed as follows:

1. Unpack fencing components from shipping crate.
2. Inspect fencing components for shipping damage.

Note: If damage is found, notify shipper immediately.

3. Verify that the following components are present:
   - Two 1300 mm panels
   - Two 900 mm panels
   - One 1250 mm door panel
   - Five fence posts
   - One modified fence post with door latch

4. Install fence panels to fence posts using the hardware provided.
Figure 14  Fencing

5. Install door rail over door opening with hardware provided.

Figure 15  Cell Door

6. Raise cell door and slide into position on door rail.
7. Close door and install remaining door rail clamp.
8. Once fencing is correctly installed, anchor fence post securely in place (refer to Appendix A for anchor requirements).

4.6 Installing the Arc Curtains

⚠️ DANGER!
Do not install the arc curtains until the cell walls have been secured. Unsecured cell walls can fall and injure personnel and damage equipment.

The arc curtains are shipped in an accessories box. Unfold arc curtains and install one curtain on inside of each cell wall section.

4.7 Installing the Safety Light Curtains

4.7.1 Installation

The light curtain components — the sender and receiver — come pre-assembled and fastened inside the center light curtain stand and two outer light curtain posts.

4.7.2 Alignment

The sender and receiver must be aligned properly. Refer to the light curtain manufacture’s literature that accompanies the robot cell for exact alignment procedures.

4.8 Installing the Auxiliary Equipment

The controller, welder, and main service disconnect are typically installed just outside the cell fencing. To install the auxiliary equipment, proceed as follows:

1. Unbolt the auxiliary equipment from the shipping skid.
2. Carefully remove plastic wrapping and cardboard from controller and welder.
3. Inspect for any shipping damage.

⚠️ Note: If damage is found, notify shipper immediately.

⚠️ WARNING!
The controller weighs approximately 150 kg (330 lbs). Be sure your lifting device is capable of handling this much weight or damage to the equipment or injury to personnel can result.

4. Using a forklift, lift the controller and remove from shipping skid.
5. Using the system drawings, place the controller and welder next to the cell.
6. Once components are correctly installed, anchor each component securely in place (refer to Appendix A for anchor requirements).

4.9 Connecting the Cables

After components are level and securely in place, the cables should be unwrapped from around the equipment and laid out according to the cable diagram included in the system drawing package. Each cable connection is clearly identified for ease of installation.

4.9.1 Connecting the Earth Ground

Each robot and NX100 controller must each be connected to an earth ground. If a ground stake is used, it should be driven to a minimum of 2.43 m (8 ft) into the soil. The soil surrounding the driven ground stake should be treated with a chemical that increases the soil conductivity in the vicinity of the driven ground stake. Longer ground stakes (or multiple ground stakes, bonded together) may be required, depending on local soil condition. The measured resistance to ground must be 100 ohms or less. To ground the robots and controller, proceed as follows:

⚠️ WARNING!
If proper earth grounds cannot be provided, do not use the equipment! Serious injury or death can occur.

Note: If the robot and the NX100 controller are within 4.57 m (15 ft) of each other, a common earth ground may be used. Otherwise, a separate earth ground must be established for each unit.

1. Connect one end of each robot earth ground cable to lug marked EARTH GROUND on bottom back of robot.
2. Connect other end of robot earth ground cable to earth ground stake.
3. Connect one end of second earth ground cable to common ground bus bar inside the controller.
4. Connect other end of second earth ground cable to earth ground stake.

4.9.2 Connecting the Robot Cables

Two cables, 1BC and 2BC, connect each robot to the controller. The 1BC cable provides position feedback from the robot to the controller. The 2BC cable provides power to the robot servo motors. To connect the robot cables, proceed as follows:

1. Unpack programming pendant and plug connector into receptacle on front door of controller.
2. Unpack two large black manipulator cables and route to controller and back of robot.
3. Carefully engaging connectors, connect one end of each cable (labeled 1BC and 2BC) to 1BC and 2BC connections on back of robot (see Figure 16). Connect other ends of 1BC and 2BC cables to the 1BC and 2BC connections on side of controller.
4.10 Connecting the Power

After all of the system components have been properly installed, connect the power to the ArcWorld II-500 as follows:

⚠️ DANGER!

Power must be connected by a qualified electrician. Electrical and grounding connections must comply with applicable portions of the national electrical code and/or local electrical codes.

1. Install 3-phase power wiring to the fused main system service disconnect. Table 1 shows size and type of wire needed.
2. Tighten screws to the torque indicated in Table 1.
3. Install an M5 lug on incoming ground wire.
4. Terminate ground wire to frame ground stud with hardware provided.

**Note:** The ArcWorld II-500 is configured for 3-phase 460/480V AC, unless other voltage was requested. If other voltage is required for your plant, you must make the necessary modifications to the transformer. For more information, refer to the electrical diagrams that came with your system.

### Table 1 Incoming Power Specifications (Decal)

<table>
<thead>
<tr>
<th>Lug Data</th>
<th>60/75° C wire</th>
</tr>
</thead>
<tbody>
<tr>
<td>Catalog No.</td>
<td>TCAL14</td>
</tr>
<tr>
<td>Wire Size</td>
<td>#14-7 Copper</td>
</tr>
<tr>
<td></td>
<td>#12-8 Aluminum</td>
</tr>
<tr>
<td>Torque</td>
<td>#14-7, 4.0 N•m (35 lb-in.)</td>
</tr>
</tbody>
</table>
4.11 **Conducting a Safety/Operation Check**

Before installing the tooling and fixtures for your application, take a few minutes to perform a safety/operation check. To conduct a safety/operation check:

1. Check that the yellow shipping bracket has been removed from the robot (see Section 4.4.1).
2. Check that the yellow shipping bolt has been removed from each barrier station (see Section 4.4.2).
3. Be sure the safety light curtains are aligned correctly.
4. Check that the cell door is closed and latched.
5. Check that all cable connections are tight.
6. Be sure the welding power source is set correctly (see the welding power source vendor’s manual).
7. Verify that incoming line power matches the input power specified on the sticker on the front of the main service disconnect.

Your ArcWorld II-500 is now ready for power-up. The system should be operated only by personnel who have received operator training from Motoman and who are familiar with the operation of this Motoman robot model. Turn main power ON, and continue the safety/operation check.

8. Check all system E-STOPS (pendant, operator station, breakaways, and controller door).
9. Check system Hold buttons.
10. Check Gate Interlock.

4.12 **Installation of Tooling and Fixtures**

Your ArcWorld II-500 system is now ready for the installation of tooling and fixtures for your application. Installation of tooling and fixtures should only be performed by personnel who are familiar with the operation of this system. Tooling and fixtures are supplied by the customer. After tooling is installed, test the positioner for proper operation.
Chapter 5

Operation

The ArcWorld II-500 is a fully integrated robotic arc welding cell. The Master job setup, and the sub-jobs programmed within it, determine how the robot performs the welding operation or other tasks. The robot welds on one station while the operator loads the other station with parts. Once the robot is finished welding, it returns to the Home position, the operator doors cycle, and the robot begins welding at the other station. The operator can now safely remove the welded piece and load new production parts onto the station.

5.1 Programming

The operation of this system is programming dependent. The following operating instructions are based on one possible configuration of this system. Your system configuration and job structure may differ slightly from that presented here; however, basic operation will be the same. For additional programming instructions, refer to the controller and operator manuals that came with your system.

Any changes made to your system configuration and/or job structure will alter the operation of this cell. Motoman recommends you do not modify the original jobs or system configuration. If modifications need to be made, they should be made to copies of these jobs and not to the originals. Modifications should only be performed by personnel who have received operator training from Motoman, and who are familiar with the operation of this Motoman system. If you have questions concerning the configuration of your system please contact the 24 hour Service Hotline, at (937) 847-3200 (refer to Section 1.4).
5.2 Daily Operation

The procedures below represent the typical operating sequence from power up to shutdown. Your basic operating procedures may vary depending on your situation.

- Perform Start-up Procedures (refer to Section 5.2.1).
- Move robot to Home position (refer to Section 5.2.2).
- Select master job (refer to Section 5.2.3).
- Perform Operation Cycle (refer to Section 5.2.4)
- Perform Shutdown Procedures (refer to Section 5.2.5)

5.2.1 Start-Up

To start up cell from a Power-Off condition, proceed as follows:

1. Set MAIN POWER switch on NX100 controller to ON.
2. Set INPUT POWER switch on welding power source to ON; power source pilot light turns on.
3. Open regulator valve on welding gas supply.
4. Make sure the enclosure door is closed and the safety plug is connected.
5. Make sure E-STOP buttons on programming pendant, controller door, and operator station are released.
6. Select TEACH mode on programming pendant.
7. Place robot in Home position.

5.2.2 Robot Home Position

To move the robot to the Home position:

1. Select TEACH mode on the programming pendant.
2. Select MAIN MENU on programming pendant touch screen.
3. Select JOB on programming pendant touch screen.
4. Select SELECT JOB on programming pendant touch screen. A job list appears on the screen.
5. Using cursor keys, move cursor to R1 SAFE job and press SELECT. The job appears on display screen.
6. Turn servo power ON by pressing SERVO ON and holding in the ENABLE switch.
7. Use the FWD button on programming pendant to jog robot to Home position.
5.2.3 Start the Master Job

With the system powered up and in TEACH mode, call up the Master job:

1. Select MAIN MENU on programming pendant touch screen.
2. Select JOB on programming pendant touch screen.
3. Select CTRL MASTER on programming pendant touch screen. Press SELECT twice to activate the Master job.
4. Select PLAY mode on programming pendant and press the PLAY ENABLE button on the controller door. Job playback operation is enabled.
5. Press SERVO ON button on the programming pendant.
6. Press START button on programming pendant. The Master job cycles, waiting for a Cycle Start input from operator station.

The ArcWorld II-500 cell is now ready for operation.

5.2.4 Perform Operation Cycle

By default, the operator doors of both weld stations will rest in the down position to permit parts loading. This condition occurs only when the robot is in the Home position and CYCLE START has not been activated on either station. The following is the typical sequence of operation for the ArcWorld II-500 cell after start-up:

1. Load Station 1 with production parts.
2. Press the CYCLE START button on operator Station 1. The operator door rises, and the robot moves to the Home 1 position.
3. The controller waits for the “OK TO WORK” input, signaling that the operator door is up and the robot is in Zone 1.
4. The robot moves into the work area and begins welding. When the robot has finished welding, it returns to the Home position, then proceeds to Station 2. As soon as the robot exits Station 1, the operator door lowers, thus giving the operator access to the welded parts on Station 1.
5. While the robot is welding at Station 1, load Station 2 with production parts.
6. Press the CYCLE START button on operator Station 2. The operator door rises and the robot begins welding at Station 2 as soon as it has finished welding at Station 1.
5.2.4.1 Re-entering Station after Cycle Latch

After a Station is loaded (while waiting on robot) and CYCLE START has been latched, safe access back into that Station can only be done using the Auto/Manual button. Failure to use the Auto/Manual button to enter a CYCLE LATCHED station causes a light curtain E-STOP.

To use the Auto/Manual button successfully, proceed as follows:

1. After parts are loaded and CYCLE START is pressed, turn the Auto/Manual button to Manual.
2. Press the CYCLE START button; the door opens.
3. Access the parts and make changes.
4. Turn the Auto/Manual button to Auto.
5. Press CYCLE START button; the door closes.

Proceed with Operation Cycle:
6. While the robot is welding on Station 2, unload welded parts from Station 1 and load new parts.
7. Activate CYCLE START to raise the operator door and permit the robot to return to Station 1.

Note: The robot will not return to Station 1 until CYCLE START has been activated, even if it has completed work at Station 2. If the robot finishes working at Station 2 before Station 1 is reloaded, the robot will return to the Home position and wait for a CYCLE START command from either station.

Once all production work is finished and the robot completes work on the last station, the robot returns to the Home position and both operator doors open to permit unloading/loading. The doors remain in the down position until CYCLE START is activated at one or both stations.

5.2.5 Shutdown

Use the following procedure to shut down the ArcWorld II-500 cell after operation is complete:

1. Make sure robot is in Home position.
2. Turn off system servo power by pressing E-STOP button on operator station or programming pendant.
3. Select TEACH mode on the programming pendant.
4. Set controller Main Power switch to OFF position.
5. Set Main Power switch on welding power source to OFF position.

The ArcWorld II-500 cell is now shut down.
5.3 **System Recovery**

When a system error or alarm occurs, you must clear the error or alarm to return the system to normal operation. The paragraphs below describe the different types of alarms and errors you may encounter and how to remedy them when you do.

5.3.1 **Alarms and Errors**

Alarms and errors will cause the program to stop. There are three levels of alarms and errors: Error Messages, Minor Alarms, and Major Alarms. For more detailed information about alarm recovery, refer to operator’s manual that came with your system.

5.3.1.1 **Error Messages**

These are simple errors such as pressing the START button when the robots are not in PLAY mode, or enabling the programming pendant when servo power is off. Clear these errors by pressing the CANCEL button on the programming pendant.

5.3.1.2 **Minor Alarms**

Minor alarms are usually programming errors. Minor alarms might occur if a circle has been programmed with fewer than three circular points, etc. Clear these errors by pressing the CANCEL button on the programming pendant.

5.3.1.3 **Major Alarms**

Major alarms are hardware failures. Major alarms might occur because of a servo tracking error or an abnormal speed. To clear these alarms, you must turn off the controller and then turn it on again.

5.3.2 **E-STOP**

An E-STOP can occur under any of the following conditions:

- Pressing E-STOP button on the operator station, programming pendant, or controller door.
- Opening the cell door on robot enclosure when system is not in TEACH mode.
- Actuating shock sensor on torch mount.

To restart the ArcWorld II-500 cell after an E-STOP condition occurs, follow the procedure below.

1. To clear E-STOP condition, perform any of the following actions that apply:
   - Release E-STOP button on operator station, programming pendant, or controller door.
   - Close cell door.
   - Clear Shock Sensor condition (refer to Section 5.3.3).

**CAUTION!**

If an emergency stop condition occurs while the positioner is sweeping, the positioner will continue the sweep when system is restarted.
2. Press SERVO ON button on operator station or programming pendant.
3. Ensure operator station is enabled.
4. Press START button on the operator station.

The ArcWorld II-500 cell is now ready to continue operation.

5.3.3 Shock Sensor Recovery

The ArcWorld welding package includes a Motoman gun mount. This mount is designed to protect the torch from damage in case of a crash. A slight deflection of the torch activates a SHOCK SENSOR message which triggers an E-STOP condition. To clear the E-STOP condition, you must override the shock sensor and move the robot clear of the impact. To override the shock sensor, proceed as follows:

1. Select MAIN MENU on programming pendant touch screen.
2. Select ROBOT on programming pendant touch screen.
3. Select OVERRUN-SENSOR on programming pendant touch screen.
4. Select RELEASE to release shock sensor.
5. Turn servo power ON by holding ENABLE switch on the programming pendant and pressing SERVO ON READY.
6. Move the robot clear of impact position.

The ArcWorld II-500 cell is now ready to continue operation.

5.3.4 Brake Release

The robot brakes are designed to protect the robot and other system components from damage in event of a system or robot failure and loss of drive power. If a system or robot failure occurs, it will be necessary to release the brakes on the robot to move it. To release the brakes, proceed as follows:

⚠️ WARNING!
Releasing brakes could cause personal injury or machine damage. Always support the axis to be released BEFORE you release it.

1. On the programming pendant, select TEACH mode and turn servo power OFF.
2. Select ROBOT on the programming pendant touch screen.
3. Select the MANUAL BRAKE RELEASE option.
4. A Warning dialog appears. Select YES in the warning dialog box.
5. Select the axis to be released using the cursor key.
6. Engage the ENABLE switch and press the Interlock and Select keys.
7. The brake for the selected axis releases.
Chapter 6
Maintenance

Table 2 provides periodic maintenance items and intervals for the ArcWorld II-500 cell. Keep in mind that the maintenance intervals serve as guidelines only. You should adjust the frequency of maintenance to suit your specific work conditions.

For periodic maintenance procedures and schedules for individual components of your ArcWorld II-500 cell, including the positioner, refer to the additional manuals that came with your system.

For maintenance requirements on the MH-series positioners, refer to Motoman MH-series Positioner Manual with MotoMount P/N 146703-1. For detailed specifications including parts lists breakdown for the Barrier Assembly, refer to the Barrier Assembly Manual, P/N 147500-1.

⚠️ CAUTION!
Use only the antifreeze provided by Motoman. Automotive antifreezes contain stop-leak additives that will clog small torch water-cooling ports and damage gaskets in water circulator pump.

Table 2 Periodic Maintenance

<table>
<thead>
<tr>
<th>FREQUENCY</th>
<th>COMPONENT</th>
<th>PROCEDURE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Daily</td>
<td>Water Circulator (Water-cooled Torch Application only)</td>
<td>Check the fluid in the water circulator. Add fluid as required. Use only distilled water and approved antifreeze (Motoman P/N 131224-1).</td>
</tr>
<tr>
<td></td>
<td>Light Curtains</td>
<td>Validate functionality</td>
</tr>
<tr>
<td>Monthly (or on condition)</td>
<td>ArcWorld Cell</td>
<td>Clean entire cell of dirt, grease and debris.</td>
</tr>
</tbody>
</table>
NOTES
Appendix A

Anchor Requirements

It is the purchaser's responsibility to determine and supply all anchoring and foundation requirements for their installation. Before installing your ArcWorld II-500 cell, refer to Table 3 to determine the anchor and foundation requirements for all the equipment used in your cell.

**WARNING!**
Do not mount robots directly to the floor without the indicated floor plate. Failure to follow floor plate requirements can result in severe damage to equipment or personal injury.

**Table 3 Minimum Recommended Equipment Anchor Requirements**

<table>
<thead>
<tr>
<th>Equipment</th>
<th>Minimum &quot;Hilti&quot; Anchor Rod Diameter and Type</th>
<th>Minimum Floor Plate Requirements</th>
<th>Minimum Foundation Requirements</th>
</tr>
</thead>
<tbody>
<tr>
<td>Robots: UP6, UP20, UP20-6, EA1400, EA1900</td>
<td>(4) 5/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>600mm x 600mm x 38.1mm</td>
<td>30&quot; x 36&quot; x 7&quot; thick, 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>Robots: UP20M, UP50, SP80 (See Note 2)</td>
<td>(4) 7/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>900mm x 900mm x 50.8mm</td>
<td>60&quot; x 60&quot; x 9&quot; thick, 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>Robots: UP120, UP130, UP165, SP100, SP160, SP250, SP400 (See Note 2)</td>
<td>(4) 7/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>1200mm x 1200mm x 50.8mm</td>
<td>72&quot; x 72&quot; x 9&quot; thick, 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>Robots: UP200</td>
<td>(8) 7/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>1200mm x 1200mm x 50.8mm</td>
<td>72&quot; x 72&quot; x 9&quot; thick, 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>Robots: UP350, UP500, SK300X</td>
<td>(8) 7/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>1500mm x 1500mm x 50.8mm</td>
<td>72&quot; x 72&quot; x 9&quot; thick, 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>Rotary Turntable Positioners:</td>
<td>5/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>Not Applicable</td>
<td>Not Applicable</td>
</tr>
</tbody>
</table>
### Table 3 Minimum Recommended Equipment Anchor Requirements

<table>
<thead>
<tr>
<th>Equipment</th>
<th>Minimum &quot;Hilti&quot; Anchor Rod Diameter and Type</th>
<th>Minimum Floor Plate Requirements</th>
<th>Minimum Foundation Requirements</th>
</tr>
</thead>
<tbody>
<tr>
<td>Trunion Style Positioners:</td>
<td>7/8&quot; HVA Chemical Style anchor (See Note 3)</td>
<td>Not Applicable</td>
<td></td>
</tr>
<tr>
<td>Peripheral Equipment:</td>
<td>1/2&quot; Kwik Bolt II Style anchor (See Note 4)</td>
<td>Not Applicable</td>
<td>3&quot; min Thick or 1.3 Embedment Depth (whichever is larger), 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>Cell Fence Posts:</td>
<td>3/8&quot; Kwik Bolt II Style anchor (See Note 4)</td>
<td>Not Applicable</td>
<td>3&quot; min Thick or 1.3 Embedment Depth (whichever is larger), 4000 psi Reinforced Concrete</td>
</tr>
</tbody>
</table>

**NOTES:**

1. Minimum Robot Lagging Requirements are based on Maximum Repulsion Forces and Hilti Anchor Design Program V3.3b.
2. SP series robots require base plates and/or risers to be level within 2 degrees. Grout if necessary.
3. Reference source: Hilti Product Technical Guide Section 4.2.1 for hardware specifications or equivalent.
4. Reference source: Hilti Product Technical Guide Section 4.3.3 for hardware specifications or equivalent.
5. Robot manual requirements calling for cast-in anchors may be substituted with the recommendations listed.
   See also [us.hilti.com](http://us.hilti.com) or [ca.hilti.com](http://ca.hilti.com) for further information.
Index

A
Alarms and Errors 37
Anchor Requirements 41
Arc Screens 19
AREA Key 15
Auto/Manual 16

B
Brake Release 20, 38

C
Components 3
Conducting a Safety/Operation Check 31
Connecting the Cables 29
Connecting the Earth Ground 29
Connecting the Power 30
Connecting the Robot Cables 30
CURSOR Key 15
Cycle Start 16

D
Daily Operation 34
Documentation 3

E
Emergency Stop (E-STOP) 13, 16
Emergency Stops (E-STOPs) 19
ENABLE Switch 15, 20
Equipment Description 11
Error Messages 37
E-STOP Recovery 37

F
Fencing 19
FLASH MEMORY Slot 15

G
General Purpose Display Area 13
General Safeguarding Tips 6
GMAW Torch 17

I
Installation 21
Installation of Tooling and Fixtures 31
Installation Safety 7
Installing the Arc Curtains 28
Installing the Controller Base 29
Installing the Fencing 27
Installing the Positioner 22, 25
Installing the Safety Light Curtains 28
Interlocked Cell Door 20
Introduction 1

K
Keypad 14

L
Layout 2

M
MAIN MENU Key 14
Maintenance 39
Major Alarms 37
Materials Required 21
Mechanical Safety Devices 7
Menu Area 13
Minor Alarms 37
Mode Selector Switch 13

N
NX100 Controller 11

O
Operation 33
Operator Station 15
Options 3
Overview 2

P
Perform Operation Cycle 35
Power Sources 17
Programming 33
Programming Pendant 12
Programming, Operation, and Maintenance Safety 8
Index

R
Removing the Shipping Bracket 25, 26
Robot Description 11
Robot Home Position 34

S
Safety 5
Safety Features 19
Safety Light Curtains 19
SELECT Key 15
Service 4
SERVO ON Key 15

Shock Sensor Recovery 38
Shutdown 36
Site Preparation 22
Starting the Master Job 35
Start-Up 34
Status Area 14
System Recovery 37

W
Welding Equipment 17
Wire Feeder 17