MOTOPOS-D200B POSITIONER INSTRUCTIONS

TYPE: YR-MPD200B-C00 (CANTILEVER SPEC.)

Upon receipt of the product and prior to initial operation, read these instructions thoroughly, and retain for future reference.

MOTOPOS INSTRUCTIONS

MOTOPOS-D200B POSITIONER INSTRUCTIONS
NX100 INSTRUCTIONS
NX100 OPERATOR’S MANUAL
NX100 MAINTENANCE MANUAL

The NX100 operator’s manual above corresponds to specific usage. Be sure to use the appropriate manual.

Part Number: 168312-1CD
Revision: 0
MANDATORY

• This instruction manual is intended to explain operating instructions and maintenance procedures primarily for the MOTOPOS.

• General items related to safety are listed in the Section 1: Safety of the NX100 instructions. To ensure correct and safe operation, carefully read the NX100 instructions before reading this manual.

CAUTION

• Some drawings in this manual are shown with the protective covers or shields removed for clarity. Be sure all covers and shields are replaced before operating this product.

• The drawings and photos in this manual are representative examples and differences may exist between them and the delivered product.

• YASKAWA may modify this model without notice when necessary due to product improvements, modifications, or changes in specifications. If such modification is made, the manual number will also be revised.

• If your copy of the manual is damaged or lost, contact a YASKAWA representative to order a new copy. The representatives are listed on the back cover. Be sure to tell the representative the manual number listed on the front cover.

• YASKAWA is not responsible for incidents arising from unauthorized modification of its products. Unauthorized modification voids your product's warranty.
Notes for Safe Operation

Read this manual carefully before installation, operation, maintenance, or inspection of the MOTOPOS and the NX100.

In this manual, the Notes for Safe Operation are classified as “WARNING”, “CAUTION”, “MANDATORY”, or “PROHIBITED”.

- **WARNING**: Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury to personnel.

- **CAUTION**: Indicates a potentially hazardous situation which, if not avoided, could result in minor or moderate injury to personnel and damage to equipment. It may also be used to alert against unsafe practices.

- **MANDATORY**: Always be sure to follow explicitly the items listed under this heading.

- **PROHIBITED**: Must never be performed.

Even items described as “CAUTION” may result in a serious accident in some situations. At any rate, be sure to follow these important items.

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**NOTE**: To ensure safe and efficient operation at all times, be sure to follow all instructions, even if not designated as “CAUTION” and “WARNING”.

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• Before operating the MOTOPOS, check that servo power is turned OFF when the emergency stop buttons on the front door of the NX100 and programing pendant are pressed. When the servo power is turned OFF, the SERVO ON LED on the programing pendant is turned OFF.

Injury or damage to machinery may result if the emergency stop circuit cannot stop the MOTOPOS during an emergency. The MOTOPOS should not be used if the emergency stop buttons do not function.

• Once the emergency stop button is released, clear the cell of all items which could interfere with the operation of the MOTOPOS. Then turn the servo power ON.

Injury may result from unintentional or unexpected MOTOPOS motion.

• Observe the following precautions when performing teaching operations within the working envelope of the MOTOPOS:
  - View the MOTOPOS from the front whenever possible.
  - Always follow the predetermined operating procedure.
  - Ensure that you have a safe place to retreat in case of emergency.

Improper or unintended MOTOPOS operation may result in injury.

• Confirm that no persons are present in the work envelope of the MOTOPOS and that you are in a safe location before:
  - Turning ON the NX100 power.
  - Operating the MOTOPOS with the programming pendant.
  - Running check operations.
  - Performing automatic operations.

Injury may result if anyone enters the working envelope of the MOTOPOS during operation. Always press an emergency stop button immediately if there is a problem. The emergency stop buttons are located on the right of the front door of the NX100 and programing pendant.
CAUTION

- Perform the following inspection procedures prior to conducting MOTOPOS teaching. If problems are found, repair them immediately, and be sure that all other necessary processing has been performed.
  - Check for problems in MOTOPOS movement.
  - Check for damage to insulation and sheathing of external wires.
- Always return the programming pendant to the hook on the NX100 cabinet after use.

The programming pendant can be damaged if it is left in work area of the MOTOPOS, on the floor, or near fixtures.

- Read and understand the Explanation of the Warning Labels in the NX100 instructions before operating the MOTOPOS.

Definition of Terms Used Often in This Manual

The MOTOPOS is the positioner for the YASKAWA industrial robot.
The MOTOPOS usually consists of MOTOPOS positioner unit, a controller unit, a programming pendant, and power cables.
In this manual, the equipment is defined as follows:

<table>
<thead>
<tr>
<th>Equipment</th>
<th>Manual Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>NX100 Controller Unit</td>
<td>NX100</td>
</tr>
<tr>
<td>NX100 Programming Pendant</td>
<td>Programming Pendant</td>
</tr>
<tr>
<td>MOTOPOS to NX100 Cable</td>
<td>Power Cable</td>
</tr>
</tbody>
</table>
Explanation of Warning Labels
The following warning labels are attached to the MOTOPOS. Always follow the warnings on the labels. Also, an identification label with important information is placed on the body of the MOTOPOS. Prior to operating the MOTOPOS, confirm the contents.

Warning Label A

![Warning Label A](image1)

Do not enter robot work area.

WARNING

Warning Label B

![Warning Label B](image2)

Moving parts may cause injury.

WARNING

Nameplate

![Nameplate](image3)

MOTOPOS

<table>
<thead>
<tr>
<th>TYPE</th>
<th>PAYLOAD</th>
<th>MASS</th>
</tr>
</thead>
<tbody>
<tr>
<td>ORDER NO.</td>
<td>DATE</td>
<td></td>
</tr>
<tr>
<td>SERIAL NO.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

YASKAWA ELECTRIC CORPORATION JAPAN
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             Rotary Axis Speed Reducer ...................... 9-8
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10 Recommended Spare Parts
1 Receiving

1.1 Contents Confirmation

Confirm the contents of the delivery when the product arrives. Standard delivery includes the following six items (information for the content of optional goods is given separately):

- Manipulator
- NX100
- Programming pendant
- Cable between the NX100 and the manipulator (2 cables or 3 cables)
- MOTOPOS
- Cable between the MOTOPOS and the NX100 (2 cables)

CAUTION

- Confirm that the MOTOPOS and the NX100 have the same order number. Special care must be taken when more than one units of MOTOPOS are to be installed.

If the numbers do not match, MOTOPOS may not perform as expected and cause injury or damage.
1.2 Checking the Order Number

Check that the order number of the MOTOPOS corresponds to the NX100. The order number is located on a label as shown below.

---

**THE MOTOPOS AND THE CONTROLLER SHOULD HAVE SAME ORDER NUMBER.**

Order No: 

Check that the MOTOPOS and the NX100 have the same order number.

---

(a) NX100 (Front View)  
(b) MOTOPOS (Side View)

**Fig. 1-1 Location of Order Number Labels**
2 Transporting

2.1 Transporting Method

---

**CAUTION**

- **Sling applications and crane or forklift operations must be performed by authorized personnel only.**

  Failure to observe this caution may result in injury or damage.

- **Avoid excessive vibration or shock during transportation.**

  The system consists of precision components. Failure to observe this caution may adversely affect the performance.

---

**NOTE**

- Check that the eyebolts are securely fastened.
- The weight of the MOTOPOS is approximately 330 kg. Use a wire rope strong enough to withstand the weight.
- Attached eyebolts are designed to support the MOTOPOS weight. Never use them for anything other than transporting the MOTOPOS.
- Avoid exerting force on the table or motors when transporting. To avoid injury, be careful when using transporting equipment other than a crane or forklift.
- Remove the eyebolts after transportation and installation, and cover the tapped holes with the attached caps. Operating the MOTOPOS with the eyebolts on may cause the jigs to interfere with the eyebolts. The eyebolts must be stored for future use in the event that the MOTOPOS must be moved again.
2.1.1 Using a Crane

As a rule, when unpacking the MOTOPOS and moving it, a crane should be used. The MOTOPOS should be lifted using wire rope threaded through attached eyebolts.

Fig. 2-1 Transporting Position
3 Installation

<table>
<thead>
<tr>
<th>WARNING</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Install the safeguarding.</strong></td>
</tr>
<tr>
<td>Failure to observe this warning may result in injury or damage.</td>
</tr>
<tr>
<td><strong>Install the MOTOPOS in a location where the MOTOPOS with a jig does not hit against anything such as the wall or the safeguarding.</strong></td>
</tr>
<tr>
<td>Failure to observe this warning may result in injury or damage.</td>
</tr>
<tr>
<td><strong>Do not start operating the MOTOPOS or turn ON the power before it is firmly anchored.</strong></td>
</tr>
<tr>
<td>The MOTOPOS may overturn and cause injury or damage.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CAUTION</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Do not install or operate a MOTOPOS which is damaged or lacks parts.</strong></td>
</tr>
<tr>
<td>Failure to observe this caution may cause injury or damage.</td>
</tr>
</tbody>
</table>
3.1 Installation of the Safeguarding

To ensure safety, be sure to install safeguarding. It prevents unforeseen accidents with personnel and damage to equipment. The following is quoted for your information and guidance.

Responsibility for Safeguarding (ISO10218)
The user of a manipulator or robot system shall ensure that safeguards are provided and used in accordance with Sections 6, 7, and 8 of this standard. The means and degree of safeguarding, including any redundancies, shall correspond directly to the type and level of hazard presented by the robot system consistent with the robot application. Safeguarding may include but not be limited to safeguarding devices, barriers, interlock barriers, perimeter guarding, awareness barriers, and awareness signals.

3.2 Mounting Procedures for MOTOPOS Baseplate

The MOTOPOS should be firmly mounted on a baseplate or foundation strong enough to support the MOTOPOS and withstand repulsion forces in acceleration and deceleration. Construct a solid foundation with the appropriate thickness to withstand maximum repulsion forces of the MOTOPOS.

The flatness for installation must be kept at 0.5 mm or less; if the flatness of the mounting face is insufficient, the shape of the MOTOPOS may deform and its functional ability may be compromised. Mount the baseplate either as shown in section "3.2.1 In Case of Installing the MOTOPOS and Manipulator on a Common Baseplate" or section "3.2.2 In Case of Mounting the MOTOPOS on the Floor".

<table>
<thead>
<tr>
<th>Table. 3-1 Maximum repulsion forces of the MOTOPOS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum torque when rotary axis used</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Maximum torque when tilting axis used</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>
3.2.1 In Case of Installing the MOTOPOS and Manipulator on a Common Baseplate

The baseplate should be rugged and durable to ensure that the MOTOPOS and the manipulator are in the correct relative position. Thickness of the baseplate and the size of the mounting anchor bolts should meet the recommendations in the manual for the manipulator to be combined.

Mount the MOTOPOS base securely with four hexagon head screws M16 (recommended length: 60 mm). Tighten the screws and anchor bolts securely so that they will not work loose during the operation.

![Fig. 3-1 Mounting the MOTOPOS Base on a Common Baseplate](image)

3.2.2 In Case of Mounting the MOTOPOS on the Floor

The floor should be strong enough to support the MOTOPOS. Construct a solid foundation with the appropriate thickness to withstand maximum repulsion forces of the MOTOPOS as shown in Table 3-1 "Maximum repulsion forces of the MOTOPOS". As a rough standard, when there is a concrete floor thickness of 200 mm or more, a baseplate (MOTOPOS baseplate thickness of 28 mm or more) can be fixed directly to the floor with anchor bolts M20. Before mounting the MOTOPOS on the floor, check the flatness, cracks, etc. of the floor. If there are any cracks and the like on the floor, they should be repaired before installation. Any thickness less than 200 mm is insufficient for mounting, even if the floor is concrete.
3.3 Location

When the MOTOPOS is installed, it is necessary to satisfy the undermentioned environmental conditions:

- Ambient Temperature: 0° to +45°C
- Humidity: 20 to 80%RH (at constant temperature)
- Free from dust, soot, or water
- Free from corrosive gas or liquid, or explosive gas
- Free from excessive vibration (Vibration acceleration: 4.9 m/s² [0.5G] or less)
- Free from large electrical noise (plasma)
- Flatness for installation: 0.5 mm or less
4 Wiring

4.1 Grounding

Follow the local regulations and electrical installation standards for grounding. The recommended grounding wire size is 5.5 mm$^2$ or more.

**NOTE**
- Never use this line sharing with other ground lines or grounding electrodes for other electric power, motor power, welding devices, etc.
- Where metal ducts, metallic conduits, or distributing racks are used for cable laying, ground in accordance with Electric Equipment Technical Standards.

**WARNING**
- **Ground resistance must be 100 $\Omega$ or less.**
  Failure to observe this warning may result in fire or electric shock.
- **Before wiring, make sure to turn OFF the primary power supply, and put up a warning sign. (ex. DO NOT TURN ON THE POWER.)**
  Failure to observe this warning may result in fire or electric shock.

**CAUTION**
- **Wiring must be performed by authorized or certified personnel.**
  Failure to observe this caution may result in fire or electric shock.
4.2 Cable Connection

There are two cables for the power supply; a power cable (1BC) and an encoder cable for detection (2BC). Connect these cables to the MOTOPOS base connectors and the NX100 respectively. Refer to Fig. 4-2(a, Fig. 4-2(b, and Fig. 4-2(c for connection between the MOTOPOS and the NX100.

4.2.1 Connection to the MOTOPOS

Before connecting the cables to the MOTOPOS, check the numbers on both cables and the MOTOPOS base connectors. Connect each cable adjusting the cable connector positions to the main key positions of the MOTOPOS, and then tighten the nut until it clicks.

4.2.2 Connection to the NX100

Remove the cover of the lower side on the NX100 side. Pass the power cable (1BC) and the encoder cable (2BC) through the opening for the cables, and then fasten bolts on the opening. Connect the power cable (1BC) to the relay connector (CNEX\(\text{PW}\) and CNEX\(\text{BRK}\)). Check the numbers on both the cable and the relay connectors before connecting. Connect the encoder cable (2BC) to the relay connector (CNEX\(\text{SG}\) and CNEX\(\text{IT}\)). Check the numbers on both the cable and the relay connector before connection.
4 Wiring
4.2 Cable Connection

Fig. 4-2(a) Connection between the MOTOPOS and the NX100
4 Wiring
4.2 Cable Connection

Fig. 4-2(b) Connection between the MOTOPOS and the NX100 (MOTOPOS Side)
4 Wiring
4.2 Cable Connection

Fig. 4-2(c) Connection between the MOTOPOS and the Power Cable (NX100 Side)
5 Basic Specifications

5.1 Basic Specifications List

*1 SI units are used in this table. However, gravitational unit is used in ( ).
*2 Conformed to ISO9283.
*3 Refer to Section 6.1 "Allowable Load" for details on the permissible moment of inertia.
5.2 Part Names and Working Axes

Fig. 5-1 Part Names and Working Axes

5.3 Baseplate Dimensions

Fig. 5-2 Baseplate Dimensions (mm)
5.4 Dimensions and Working Envelope

Fig. 5-3 Dimensions and Working Envelope
6 Load Specifications and Jig Mounting Section

6.1 Allowable Load

This section describes the allowable values and various limitations. The payload of the MOTOPOS is 200 kg. The moment and moment of inertia are limited as shown in Table 6-1 "Moment and Total Inertia".

Table 6-1 Moment and Total Inertia

<table>
<thead>
<tr>
<th>Axis Name</th>
<th>Moment N·m (kgf·m)</th>
<th>GD²/4 Total Inertia kgf·m²</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tilting Axis</td>
<td>686 (70)</td>
<td>35</td>
</tr>
<tr>
<td>Rotary Axis</td>
<td>196 (20)</td>
<td>17</td>
</tr>
</tbody>
</table>

*1 ( ): Gravitational unit

When the volume load is relatively small, refer to the moment rating shown in Fig. 6-1 "Moment Rating".
The allowable total inertia is calculated when the moment is at the maximum. Contact your Yaskawa representative when only inertia moment, or load moment is small while inertia moment is large. Also, when the load is combined as a force but a mass, contact your Yaskawa representative.
6.2 Details of Jig Mounting Face

The jig mounting dimensions are shown in Fig. 6-2 "Details of Jig Mounting Face". It is recommended that the table and the jig be mounted using an inside dowel and dowel pin, or two dowel pins. The dowel pins are to be prepared by customers.

![Diagram of Jig Mounting Face]

**NOTE** Wash OFF anti-corrosive paint (solid color) on the jig mounting surface with thinner or light oil before mounting the tools.

Provide a space for positioner maintenance on the jig side as shown in the following figure.
7 System Application

7.1 Internal User I/O Wiring Harness and Air Line

For the drives of the devices such as a jig, internal user I/O wires and an air line are built into the MOTOPOS as shown in Fig. 7-1 "Internal Wires and Air Line".

YR-MPD200B-A00: Internal user I/O wiring harness: 0.5 mm² × 6 wires: shielded
AWG 24 × 2 wires
AWG 22 × 2 wires (one shielded wire)

Air line: Inner diameter: 8 mm × 2 lines

Connector pins are assigned as shown in Fig. 7-1 "Internal Wires and Air Line". Wiring must be performed by user.

The allowable current for Internal user I/O wiring harness: 3 A or less for each wire (30 A or less in total)

The maximum pressure for the air line: 490 kPa (5 kgf/cm²) or less
# System Application

## 7.1 Internal User I/O Wiring Harness and Air Line

![Diagram of internal wires and air line](image)

### Fig. 7-1 Internal Wires and Air Line

### Table 7-1 List of Connector Types

<table>
<thead>
<tr>
<th>Positioner</th>
<th>Name</th>
<th>Connector Type</th>
<th>Applicable Pin No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>YR-MPD200B-C00</td>
<td>Connector base section: Internal I/O wiring harness</td>
<td>JL05-2A18-1PC (JL05-6A18-1SC: Optional)</td>
<td>1 to 6</td>
</tr>
<tr>
<td></td>
<td>Table section: Internal I/O wiring harness</td>
<td>Crimped contact-pin PC2005-W (PC2005-M: Optional)</td>
<td>1 to 6</td>
</tr>
</tbody>
</table>
The internal wiring harness and the air line on the table side are designed to be pulled out from the center part. Provide a hole for pullout on the jig base plate. Be sure to mount a cover on the hole to avoid spatters going inside the MOTOPOS. Refer to a mounting example in Fig. 7-2 "Pullout Section of Internal Wiring Harness and Air Line".

**NOTE**

Be sure to provide a cover for the internal user I/O wiring harness and air line pullout section on the table side. Otherwise, spatters may go inside the MOTOPOS resulting in a failure.
7.2 Minus Cable for Welding

Minus cable for welding is equipped inside the MOTOPOS.

- Allowable current for minus cable: 500 A

The minus cable on the table side is connected directly to the table. It is connected to the jig base plate through the table, requiring no minus cable on the jig side. However, to connect the cable to any place near the welded part, connect the minus cable to the jig base plate as shown in Fig. 7-3 "Minus Wire Connection".

![Fig. 7-3 Minus Wire Connection](image-url)
8 Electrical Equipment Specification

8.1 Position of Limit Switch

The overrun limit switch is provided only for the tilting axis. For the location, refer to Fig. 8-1 "Position of Limit Switch".

Fig. 8-1 Position of Limit Switch
High reliability connectors which can be easily put on and removed are used in each connector part.
9 Maintenance and Inspection

### WARNING

- **Before maintenance or inspection, be sure to turn OFF the main power supply, and put up a warning sign. (ex. DO NOT TURN THE POWER ON.)**

Failure to observe this warning may result in electric shock or injury.

### CAUTION

- **Maintenance and inspection must be performed by specified personnel.**

Failure to observe this caution may result in electric shock or injury.

- **For disassembly or repair, contact your Yaskawa representative.**

- **Do not remove the motor, or release the brake.**

Failure to observe this caution may result in injury from unexpected turning of the table.

## 9.1 Inspection Interval

Proper inspections are essential not only to assure that the mechanism will be able to function for a long period, but also to prevent malfunctions and assure safe operation. Inspection intervals are classified into six levels as shown in Table 5. Conduct periodical inspections according to the inspection schedule in Table 9-1 "Inspection Items".

In Table 9-1 "Inspection Items", the inspection items are categorized by 3 types of operations: operations which can be performed by personnel authorized by the user, operations which can be performed by personnel being trained, and operations which can be performed by service company personnel. Only specified personnel are to do inspection work.

- The inspection interval depends on the total servo operation time.
- For axes which are used very frequently other than arc welding, it is recommended that inspections be conducted at shorter intervals. Contact your Yaskawa representative.
### Table 9-1 Inspection Items

<table>
<thead>
<tr>
<th>Items*4</th>
<th>Inspection Interval</th>
<th>Method</th>
<th>Operation</th>
<th>Inspection Charge</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Daily</td>
<td>1000 H Cycle</td>
<td>6000 H Cycle</td>
<td>12000 H Cycle</td>
</tr>
<tr>
<td>1</td>
<td>Alignment mark</td>
<td>O</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Visual</td>
<td>Check alignment mark accordance and damage at the home position.</td>
</tr>
<tr>
<td>2</td>
<td>External lead</td>
<td>O</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Visual</td>
<td>Check for damage and deterioration of leads.</td>
</tr>
<tr>
<td>3</td>
<td>Working area and whole exterior of MOTOPOS</td>
<td>O</td>
<td>Visual</td>
<td>Clean the work area if dust or spatter is present. Check for damage and outside cracks.</td>
</tr>
<tr>
<td>4</td>
<td>Tilting axis motor</td>
<td>O</td>
<td>Visual</td>
<td>Check for grease leakage.*5</td>
</tr>
<tr>
<td>5</td>
<td>Earth brush</td>
<td>O</td>
<td>Air blow</td>
<td>Check for damage, deterioration and wear of brushes. Remove wear powder or spatter.</td>
</tr>
<tr>
<td>6</td>
<td>Baseplate mounting bolts</td>
<td>O</td>
<td>Spanner Wrench</td>
<td>Tighten loose bolts. Replace if necessary.</td>
</tr>
<tr>
<td>7</td>
<td>Cover mounting screws</td>
<td>O</td>
<td>Screwdriver, Wrench</td>
<td>Tighten loose bolts. Replace if necessary.</td>
</tr>
<tr>
<td>8</td>
<td>Connectors</td>
<td>O</td>
<td>Manual</td>
<td>Check for loose connectors and tighten if necessary.</td>
</tr>
<tr>
<td>9</td>
<td>Air line</td>
<td>O</td>
<td>Auditory</td>
<td>Check for air leakage.</td>
</tr>
<tr>
<td>10</td>
<td>Wire harness in MOTOPOS</td>
<td>O</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Check for conduction between the main connector of base and end connector with manually shaking the wire. Check for wear of protective spring.*1</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Replace.*2</td>
</tr>
<tr>
<td>11</td>
<td>Battery pack in MOTOPOS</td>
<td>O</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Replace the battery pack when the battery alarm occurs or the MOTOPOS drove for 36000H.*4</td>
</tr>
<tr>
<td>12</td>
<td>Tilting axis speed reducer</td>
<td>O</td>
<td>O</td>
<td>Grease Gun</td>
</tr>
</tbody>
</table>
9. Maintenance and Inspection

9.1 Inspection Interval

- **When checking for conduction with multimeter, remove connectors on detector side for each axis from the motor.**
- **Wire harness in MOTOPOS should be replaced at 24000H inspection.**
- **For the grease, refer to Table 9-2 "Inspection Parts and Grease Used".**
- **Corresponds to the numbers in Fig. 9-1 "Inspection Parts and Inspection Numbers".**
- **A grease leakage indicates the possibility that grease has seeped into the motor, which can cause a motor breakdown. Contact your Yaskawa representative.**

### Table. 9-1 Inspection Items

<table>
<thead>
<tr>
<th>Items*4</th>
<th>Inspection Interval</th>
<th>Method</th>
<th>Operation</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Daily</td>
<td>1000 H Cycle</td>
<td>6000 H Cycle</td>
</tr>
<tr>
<td>13</td>
<td></td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>14</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*1 When checking for conduction with multimeter, remove connectors on detector side for each axis from the motor.
*2 Wire harness in MOTOPOS should be replaced at 24000H inspection.
*3 For the grease, refer to Table 9-2 "Inspection Parts and Grease Used".
*4 Corresponds to the numbers in Fig. 9-1 "Inspection Parts and Inspection Numbers".
*5 A grease leakage indicates the possibility that grease has seeped into the motor, which can cause a motor breakdown. Contact your Yaskawa representative.

![Fig. 9-1 Inspection Parts and Inspection Numbers](image)

### Table. 9-2 Inspection Parts and Grease Used

<table>
<thead>
<tr>
<th>No.</th>
<th>Grease Used</th>
<th>Inspected Parts</th>
</tr>
</thead>
<tbody>
<tr>
<td>12, 13</td>
<td>Molywhite RE No. 00</td>
<td>All axes speed reducers</td>
</tr>
</tbody>
</table>

The numbers in the above table correspond to the numbers in Table 9-1 "Inspection Items".
9.2 Notes on Maintenance Procedures

9.2.1 Battery Pack Replacement

The battery pack is mounted in the location indicated in Fig. 9-2 "Battery Location". If a battery alarm occurs in the NX100, replace the battery according to the following procedure:

1. Turn OFF the NX100 main power supply.
2. Remove the cover of the tilting frame section and pull out the battery pack to replace.
3. Remove the battery pack mounting screw.
4. Remove the plastic tape (insulation tape) protecting the connection part of the battery pack in the MOTOPROS.
5. Connect the new battery.
6. Remove the old battery.

---

New battery pack

Cross-slot APS screw M6 ×12 (3 screws)

for fixing earth leads

Cross-slot APS screw M5 ×12

Battery pack: HW8471030-A

Cross-slot APS screw M6 ×12 (4 screws)

Washer M6

Connector base: HS0300701

Fig. 9-2 Battery Location

Internal wire

See procedure 4 Battery pack before replacement

See procedure 6

See procedure 7

a: Crimped contact-pin (Pin)
b: Crimped contact-pin (Socket)
9.2 Notes on Maintenance Procedures

- Remove the old battery pack after connecting the new one so that the encoder absolute data do not disappear.

- Protect the connection part of the battery pack in the MOTOPOS with plastic tape (insulation tape).

- Mount the battery pack with the screws, and then reinstall the cover to complete the replacement.

- Be sure not to pinch cables in reinstalling the cover of the frame section.
9.2.2 Grease Replenishment/Exchange for Tilting Axis Speed Reducer

**Grease Replenishment (Refer to Fig. 9-4 "Tilting Axis Speed Reducer Diagram").**

1. Remove the motor cover.
2. Remove the plug from Bo grease exhaust port.

**NOTE**
If grease is added with the plug on, the grease will go inside the motor and may damage it. Never fail to remove the plug before the grease injection.

3. Inject the grease into the Bi grease inlet using a grease gun.

**Grease type: Molywhite RE No.00**

4. Move the tilting axis for a few minutes to discharge the excess grease.
5. Wipe the Bo grease exhaust port with a cloth and reinstall the plug. (Apply the Modifier silicon Caulk on the thread part of the plug.)
6. Reinstall the motor cover.
9.2 Notes on Maintenance Procedures

- Grease Exchange (Refer to Fig. 9-4 "Tilting Axis Speed Reducer Diagram").

1. Remove the motor cover.
2. Remove the plug from Bo grease exhaust port.

**NOTE** If grease is added with the plug on, the grease will go inside the motor and may damage it. Never fail to remove the plug before the grease injection.

3. Inject the grease into the Bi grease inlet using a grease gun.

   **Grease type: Molywhite RE No.00**

4. The grease replacement is completed when new grease appears in the Bo grease exhaust port. The new grease can be distinguished from the old grease by color.
5. Move the tilting axis for a few minutes to discharge the excess grease.
6. Wipe the Bo grease exhaust port with a cloth and reinstall the plug. (Apply the Modifier silicon Caulk on the thread part of the plug.)
7. Reinstall the motor cover.
9.2.3 Grease Replenishment/Exchange for Rotary Axis Speed Reducer

![Rotary Axis Speed Reducer Diagram](image.png)

- **Grease Replenishment (Refer to Fig. 9-5 "Rotary Axis Speed Reducer Diagram").**
  1. Stop the tilting axis within ±30° from the home position.
  2. Remove the plug from To grease exhaust port.

**NOTE**

If grease is added with the plug on, the grease will go inside the motor and may damage it. Never fail to remove the plug before the grease injection.

3. Inject grease into the Ti grease inlet using a grease gun.

   **Grease type:** Molywhite RE No.00

4. Move the rotary axis for a few minutes to discharge the excess grease.
5. Wipe the To grease exhaust port with a cloth and reinstall the plug. (Apply the Modifier silicon Caulk on the thread part of the plug.)
9.2 Notes on Maintenance Procedures

Grease Exchange (Refer to Fig. 9-5 "Rotary Axis Speed Reducer Diagram").

1. Remove the plug from To grease exhaust port.

   **NOTE** If grease is added with the plug on, the grease will go inside the motor and may damage it. Never fail to remove the plug before the grease injection.

2. Inject grease into the Ti grease inlets using a grease gun.

   Grease type: Molywhite RE No.00

3. The grease replacement is completed when new grease appears in the To grease exhaust port. The new grease can be distinguished from the old grease by color.

4. Move the rotary axis for a few minutes to discharge the excess grease.

5. Wipe the To grease exhaust port with a cloth and reinstall the plug. (Apply the Modifier silicon Caulk on the thread part of the plug.)
It is recommended that the parts and components in the following table be kept in stock as spare parts for the MOTOPOS. Product performance cannot be guaranteed when using spare parts from any company other than Yaskawa. The spare parts are ranked as follows:

- Rank A: Expendable and frequently replaced parts
- Rank B: Parts for which replacement may be necessary as a result of frequent operation
- Rank C: Drive Unit

To replace parts in Rank B or Rank C, contact your Yaskawa representative.

<table>
<thead>
<tr>
<th>Rank</th>
<th>Parts No.</th>
<th>Name</th>
<th>Type</th>
<th>Manufacturer</th>
<th>Qty</th>
<th>Qty per Unit</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>1</td>
<td>Grease</td>
<td>Molywhite RE No. 00</td>
<td>Yaskawa</td>
<td>16 kg</td>
<td>-</td>
<td>Speed reducers for all axes</td>
</tr>
<tr>
<td>A</td>
<td>2</td>
<td>Silicon Rubber Compound Tube</td>
<td>Silicon Caulk</td>
<td>Konishi Co., Ltd.</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>3</td>
<td>Battery Pack</td>
<td>HW847030-A</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>B</td>
<td>4</td>
<td>Brush Unit</td>
<td>HS9381711-A</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>B</td>
<td>5</td>
<td>Tilting Axis Speed Reducer</td>
<td>HW9381751-A</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
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<tr>
<td>B</td>
<td>6</td>
<td>Rotary Axis Speed Reducer</td>
<td>HW9280663-A</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
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<tr>
<td>C</td>
<td>7</td>
<td>AC Servomotor for Tilting Axis</td>
<td>SGMRS-12A2B-YR11</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
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<tr>
<td>C</td>
<td>8</td>
<td>AC Servomotor for Rotary Axis</td>
<td>SGMRS-06A2B-YR11</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
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<tr>
<td>C</td>
<td>9</td>
<td>Wire Harness in MOTOPOS</td>
<td>HS0170258-A</td>
<td>Yaskawa</td>
<td>1</td>
<td>1</td>
<td></td>
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</tbody>
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MOTOPOS-D200B POSITIONER INSTRUCTIONS

Specifications are subject to change without notice for ongoing product modifications and improvements.

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