Upon receipt of the product and prior to initial operation, read these instructions thoroughly and retain for future reference.

**MOTOMAN INSTRUCTIONS**

- MOTOMAN MA1440 INSTRUCTIONS
- DX200 INSTRUCTIONS
- DX200 OPERATOR’S MANUAL
- DX200 MAINTENANCE MANUAL

The DX200 operator’s manual above corresponds to specific usage. Be sure to use the appropriate manual.
MANDATORY

- This system manual provides an overview of the Motoman ArcWorld® C-50 Series system. It gives general information about the system, a description of its major components, and the procedures for installation, system operation, and preventive and repair maintenance. Be sure to read and understand this manual thoroughly before installing and operating the ArcWorld® C-50 Series system.

- General items related to safety are listed in Section 1 of the DX200 Controller Manual. To ensure correct and safe operation, carefully read the DX200 Controller Manual before reading this manual.

CAUTION

- Some drawings in this manual are shown with the protective covers or shields removed for clarity. Be sure that all covers and shields are replaced before operating this product.

- The drawings and photos in this manual are representative examples, and differences may exist between them and the delivered product.

- YASKAWA may modify this model without notice when necessary due to product improvements, modifications, or changes in specifications.

- If such a modification is made, the manual number will also be revised.

- If your copy of the manual is damaged or lost, contact a YASKAWA representative to order a new copy. The representatives are listed on the back cover. Be sure to tell the representative the manual number listed on the front cover.

- YASKAWA is not responsible for incidents arising from unauthorized modification of its products. Unauthorized modification voids your product's warranty.
We suggest that you obtain and review a copy of the ANSI/RIA National Safety Standard for Industrial Robots and Robot Systems (ANSI/RIA R15.06-2012). You can obtain this document from the Robotic Industries Association (RIA) at the following address:

Robotic Industries Association  
900 Victors Way  
P.O. Box 3724  
Ann Arbor, Michigan 48106  
TEL: (734) 994-6088  
FAX: (734) 994-3338  
www.roboticsonline.com

Ultimately, well-trained personnel are the best safeguard against accidents and damage that can result from improper operation of the equipment. The customer is responsible for providing adequately trained personnel to operate, program, and maintain the equipment. NEVER ALLOW UNTRAINED PERSONNEL TO OPERATE, PROGRAM, OR REPAIR THE EQUIPMENT!

We recommend approved Yaskawa training courses for all personnel involved with the operation, programming, or repair of the equipment.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications.
Notes for Safe Operation

Read this manual carefully before installation, operation, maintenance, or inspection of the Motoman ArcWorld® C-50 Series system.

In this manual, the Notes for Safe Operation are classified as “WARNING,” “CAUTION,” “MANDATORY,” or “PROHIBITED.”

⚠️ WARNING

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury to personnel.

⚠️ CAUTION

Indicates a potentially hazardous situation which, if not avoided, could result in minor or moderate injury to personnel and damage to equipment. It may also be used to alert against unsafe practices.

⚠️ MANDATORY

Always be sure to follow explicitly the items listed under this heading.

🚫 PROHIBITED

Must never be performed

Even items described as “CAUTION” may result in a serious accident in some situations. At any rate, be sure to follow these important items.

To ensure safe and efficient operation at all times, be sure to follow all instructions, even if not designated as “CAUTION” and “WARNING.”
WARNING

• Before operating the manipulator, check that servo power is turned OFF by pressing the EMERGENCY STOP buttons on the operator station or Programming Pendant (refer to Fig. 1). When servo power is turned OFF, the SERVO ON LED on the Programming Pendant is turned OFF.

Injury or damage to machinery may result if the Emergency Stop circuit cannot stop the manipulator during an emergency. The manipulator should not be used if the EMERGENCY STOP buttons do not function.

*Fig. 1: EMERGENCY STOP Button*

• Release the EMERGENCY STOP button (refer to Fig. 2). Once this button is released, clear the cell of all items which could interfere with the operation of the manipulator. Then turn servo power ON.

Injury may result from unintentional or unexpected manipulator motion.

*Figure 2: Release of EMERGENCY STOP Button*

• Observe the following precautions when performing teaching operations within the P-point maximum envelope of the manipulator:
  – View the manipulator from the front whenever possible.
  – Always follow the predetermined operating procedure.
  – Ensure that you have a safe place to retreat to in case of emergency.

Improper or unintended manipulator operation may result in injury.

• Confirm that no person is present in the P-point maximum envelope of the manipulator and that you are in a safe location before:
  – Turning on the power for the DX200 controller.
  – Moving the manipulator with the Programming Pendant.
  – Running the system in the check mode.
  – Performing automatic operations.

Injury may result if anyone enters the P-point maximum envelope of the manipulator during operation. Always press an EMERGENCY STOP button immediately if there is a problem. The EMERGENCY STOP buttons are located on the operator station and on the Programming Pendant.
Definition of Terms Used Often in This Manual

The MOTOMAN manipulator is the YASKAWA industrial robot product.

The manipulator usually consists of the controller, the Programming Pendant, and supply cables.

In this manual, the equipment is designated as follows:

<table>
<thead>
<tr>
<th>Equipment</th>
<th>Manual Designation</th>
</tr>
</thead>
<tbody>
<tr>
<td>DX200 controller</td>
<td>DX200</td>
</tr>
<tr>
<td>DX200 Programming Pendant</td>
<td>Programming Pendant</td>
</tr>
<tr>
<td>Cable between the manipulator and the controller</td>
<td>Manipulator cable</td>
</tr>
</tbody>
</table>
Explanation of Warning Labels

The following warning labels are attached to the manipulator (refer to Fig. 3).

Always follow the warnings on the labels.

An identification label with important information is on the top back of the S-head casting of the manipulator. Prior to operating the manipulator, confirm the contents.

Figure 3: Warning Labels Location

WARNING Label A

WARNING Label B

Nameplate:

WARNING Label A:

WARNING Moving parts may cause injury

WARNING Label B:

WARNING Do not enter robot work area.
# Table of Contents

1 Introduction ..................................................................................................................................... 1-1
   1.1 About This Document ........................................................................................................ 1-1
   1.2 System Overview .................................................................................................................. 1-2
      1.2.1 System Layout ............................................................................................................. 1-4
      1.2.2 Major Components ...................................................................................................... 1-4
      1.2.3 Optional Equipment ...................................................................................................... 1-4
      1.2.4 Theory of Operation and Safe Guarding ...................................................................... 1-5
         1.2.4.1 System Teaching ................................................................................................. 1-7
         1.2.4.2 System Operation ................................................................................................. 1-7
         1.2.4.3 Key Safety Devices: ............................................................................................ 1-8
         1.2.4.4 Safety Logic Implementation (all cells): ............................................................. 1-9
   1.3 Reference Documentation ...................................................................................................... 1-15
      1.3.1 Location of Operations in Reference Documentation ................................................ 1-15
   1.4 Customer Service Information ............................................................................................. 1-18

2 Equipment Description ................................................................................................................ 2-1
   2.1 Robot Description .................................................................................................................. 2-1
   2.2 DX200 Controller .................................................................................................................. 2-1
      2.2.1 Programming Pendant ............................................................................................... 2-2
   2.3 Operator Station ................................................................................................................... 2-4
      2.3.1 CYCLE START/CYCLE LATCHED Button .................................................................. 2-4
      2.3.2 EMERGENCY STOP (E-STOP) Button ....................................................................... 2-4
      2.3.3 POSITIONER AUTO/MANUAL .................................................................................. 2-4
   2.4 Work Stations ....................................................................................................................... 2-5
      2.4.1 Stationary Weld Tables ............................................................................................... 2-5
      2.4.2 MH185 Headstock (ArcWorld C-50S/52S Only) ....................................................... 2-5
   2.5 Welding Equipment ............................................................................................................... 2-6
      2.5.1 Power Sources ............................................................................................................ 2-6
      2.5.2 Wire Feeder ............................................................................................................... 2-6
      2.5.3 GMAW Torch ............................................................................................................ 2-6
   2.6 Safety Features ..................................................................................................................... 2-6
      2.6.1 Part Loading Door(s) ............................................................................................... 2-7
      2.6.2 Arc Screens .............................................................................................................. 2-7
      2.6.3 Safety Fencing ............................................................................................................ 2-7
2.6.4 EMERGENCY STOP (E-STOP) Buttons .............................................................. 2-7
2.6.5 ENABLE Switch .............................................................................................. 2-8
2.6.6 Robot Braking System ...................................................................................... 2-8
2.6.7 Interlocked Work-cell Door ............................................................................... 2-8

3 Installation ............................................................................................................ 3-1

3.1 Materials Required .............................................................................................. 3-1

3.1.1 Customer-supplied Items ............................................................................... 3-1
3.1.2 Recommended List of Hand Tools and Equipment ........................................... 3-2

3.2 Site Preparation .................................................................................................. 3-3

3.3 Installing the System Base ................................................................................... 3-4

3.4 Cable Connections .............................................................................................. 3-6

3.4.1 Connection to Local Electrical Service ......................................................... 3-6
3.4.1.1 DX200 Controller .................................................................................... 3-6
3.4.1.2 Welding Power Sources .......................................................................... 3-6

3.5 Safety/Operation Check ....................................................................................... 3-7

3.6 Installation of Tooling and Fixtures ..................................................................... 3-8

4 Operation ............................................................................................................. 4-1

4.1 Programming ........................................................................................................ 4-1

4.2 Daily Operation ................................................................................................... 4-2

4.2.1 Start-up Procedure ......................................................................................... 4-2
4.2.2 Robot HOME Position .................................................................................... 4-3
4.2.3 Master Job ....................................................................................................... 4-3
4.2.4 Operation Cycle ............................................................................................... 4-4
4.2.5 Shutdown Procedure ....................................................................................... 4-4

4.3 System Recovery ................................................................................................ 4-5

4.3.1 Alarms and Errors ......................................................................................... 4-5
4.3.1.1 Error Messages ....................................................................................... 4-5
4.3.1.2 Minor Alarms ........................................................................................... 4-5
4.3.1.3 Major Alarms ........................................................................................... 4-5
4.3.2 Emergency Stop (E-STOP) Recovery .............................................................. 4-6
4.3.3 Shock Sensor Recovery .................................................................................. 4-6

5 Maintenance ......................................................................................................... 5-1

6 Anchoring ............................................................................................................. 6-1

Appendix A ................................................................................................................ ChecklistA-1
1 Introduction

1.1 About This Document

The ArcWorld® C-50 Series is part of the ArcWorld family of standardized arc-welding solutions. The ArcWorld® C-50 Series consists of the following cells:

- ArcWorld C-50
- ArcWorld C-52
- ArcWorld C-50S
- ArcWorld C-52S

1.1 About This Document

This system manual provides a “first look” and overview of the complete Motoman ArcWorld® C-50 Series system. You should read and understand this system manual before moving on to the more detailed documentation that is included with your ArcWorld® C-50 Series system. Although basic in content, the system manual is intended for personnel who have received operator training from Motoman and who are familiar with the operation of this particular Motoman system. For more detailed information on any specific component or peripheral of the ArcWorld® C-50 Series system, please review the full documentation package that is included with your ArcWorld® C-50 Series system (refer to section 1.3).

This manual documents a standard Motoman system. If your system is a custom or modified, use this manual with the drawings, schematics, and parts listing (Bill of Material) for your specific system. The drawings, schematics, and parts listing are included in the documentation package supplied with your Motoman system.

This system manual contains the following chapters:

chapter 1 “Introduction”

This chapter provides general information about the ArcWorld® C-50 Series and its components, a list of reference documents, and customer service information.

chapter 2 “Equipment Description”

This chapter provides a description of the major components of the ArcWorld® C-50 Series system.

chapter 3 “Installation”

This chapter provides instructions for the setup and installation of the ArcWorld® C-50 Series systems.

chapter 4 “Operation”

This chapter provides instructions for basic operation of the ArcWorld® C-50 Series systems. It also provides procedures for start-up, loading, normal operation, fault recovery, and shutdown.

chapter 5 “Maintenance”

This chapter contains a table listing periodic maintenance requirements for the components of the ArcWorld® C-50 Series cells.

chapter 6 “Anchoring”

This chapter gives foundation and anchoring suggestions for components of the ArcWorld® C-50 Series system.
1.2 System Overview

Motoman’s classic ArcWorld® C-50 Series robotic solutions are high-performance, pre-engineered work cells that are ideal for smaller part fabrication at medium to high volumes. The system is designed around a high-performance MA-series Motoman robot and DX200 controller and includes an integrated welding package, operator interface, and total safety environment. Safety features include load station(s) interlocked with dual-channel safeguards, interlocked access doors, and safety fencing.

High-speed motorized doors to provide access to the cell for loading and unloading of production parts. The ArcWorld C-50 has one robot work area, while the ArcWorld C-52 has two robot work areas. The two work areas enable the operator to load and unload parts from one station while the robot is working at the other. Stationary weld tables are standard for the ArcWorld C-50/52. The “S” designation indicates that the system includes MH185 servo-driven headstocks for positioning of parts. Fig. 1-1 illustrates the layout and component locations for the ArcWorld® C-50 Series system.

Safeguards for the system complement the system operation while protecting the various people that will program, operate, and/or provide maintenance to the system. Possible pinch points and other hazards from the risk assessment process determined needed safeguards and interlocks. While the system design safeguards the support staff, it does not protect against misuse of the system. Misuse of the system includes, but is not limited to climbing over/under barriers, climbing over/under interlocked doors, or disabling/bypassing of system interlocks.

During the install and commissioning process the end user must ensure tooling, ancillary equipment, etc. have not introduced additional hazards into the design. This evaluation ensures that the system will provide a safe and reliable operation. The Risk Assessment document should be reviewed for installation of the system and prior to operation. Any changes and additions to the system require full review of the Risk Assessment document.
This manual is for a standard Motoman system. If your system is a custom or modified system, please use the drawings and Bill of Material (BOM) provided with the system for troubleshooting and spares provisioning.
1.2 System Overview

1.2.1 System Layout
All components of the ArcWorld® C-50 Series are mounted to a common platform for quick installation and relocation. The robotic cell is fully enclosed by safety fencing and an interlocking door. The interlocked station doors allow the operator to load parts. All operator controls, including those on the controller and welding power supply, are accessible from outside of the robotic enclosure.

1.2.2 Major Components
The ArcWorld® C-50 Series includes the following major components:

- Motoman MA1440 manipulator
- DX200 controller
- Common Equipment Base
- Stationary mount posts for weld table(s) (ArcWorld C-50/52)
- MH185 servo-driven headstock(s) (ArcWorld C-50S/52S)
- One Programming Pendant (located on DX200 controller)
- Operator Station
- Welding equipment, including the following:
  - Welding power supply
  - Welding torch (air-cooled)
  - Wire feeder
  - Applicable welding interface
  - Torch mount
- Safety equipment, including the following:
  - Heavy-gauge, wire-mesh safety fencing
  - Arc curtains (cover the safety fencing)
  - Interlocked cell door
  - Motor driven, safety interlocked doors

1.2.3 Optional Equipment
The following optional equipment is available for use with the ArcWorld® C-50 Series systems:

- Torch tender
- Wire cutter
- ComArc™ (seam tracking)
- Water circulator
- Touch Sense™ Starting Point detection unit
- Equipment bases
- Weld table top
1.2.4 Theory of Operation and Safe Guarding

The DX200 “ArcWorld C” series of cells are designed to accommodate a single MA1440 robot. The cells are available in a number of configurations including:

- AWC-50 - Single station with flat table
- AWC-52 - Two stations with flat table
- AWC-50S - Single station with single axis 185 kg positioner
- AWC-52S - Two stations each with a 185 kg positioner

The cell is for arc welding applications where the robot controller and welding power source are located behind the cell. Two sliding doors with safety interlocks allow access from either side. The MA1440 sits on a 600mm raiser in the center of the cell. Mounting provisions in the base are for an in-cell torch cleaning station. In the AWC-50 and AWC-52 cells, a fixed table(s) is located in front of the robot providing a flat surface for mounting tooling. The AWC-50S and AWC-52S have the MHT-185 positioner(s) mounted to a basic frame. A powered roll-up door comes down to waist height to prevent/gain access to the table/185 positioner and the robot. Below waist height, table structure’s and sheet metal covers prevent access. A three button post mounted operator station is located on the fence post(s). This operator station provides a [Cycle Start] push button, [Auto/Manual] selector switch, and an [E-Stop] button.

Fig. 1-2(a): AWC-50 Rear View
Fig. 1-2(b): AWC-50 Front/Side View

Fig. 1-2(c): AWC-52S Rear View
1.2.4.1 System Teaching

All systems are programmed from either within the system or from the front part loading location. In order to program the robot, the controller needs to be in “Teach Mode” from the selector switch on the front of the pendant. This “Teach Mode” selection will limit all robot and external axes speeds to 250 mm/min while in this mode. While in “Teach Mode” the robot's safety interlocks for the two gate interlocks and the roll-up door interlock can be in any state (open or closed). In order for the robot's servo motors to be turned on, the "deadman" switch on the teach pendant needs to be maintained. Once servo power is on, the operator is able to program the part from inside or outside the cell as desired using the teach pendant. During teaching on a 50S or 52S cell, the 185 kg headstock positioners are free to rotate as commanded from the programming pendant. Also while in “Teach Mode”, the roll-up door will operate at full speed as commanded by either the INFORM logic in a job, I/O on the teach pendant, or the [Cycle Start] button press on the operator station.

1.2.4.2 System Operation

Once completing the path and logic programming, you can place the system into operation after meeting the following conditions:

1. Placing programming pendant in “Play” mode
2. Closing the gate
3. Applying servo power to the programming pendant
4. The [Start] button on the pendant needs to be pressed to begin execution of the INFORM job. Once applying the servo power and job execution begins, then normal cell production can begin.

Normal cell production begins with the assumption that the roll-up door is in the raised position. Anytime the roll-up door is open, the robot will operate at a limited speed of 500 mm/sec maximum via the speed limiting function of the FSU. FSU Zones ensure that the robot remains behind the tooling while the roll-up doors are open allowing the robot to access a torch cleaner or tip-change station while at the limited speed. While the roll-up doors are open, the headstock positioners in the AWC-50S or AWC-52S cells are in “Standstill Monitoring” mode via the FSU, when the operator approaches the cell, walks beneath the roll-up door, loads the part into the fixture. Once the part has been loaded, the operator will step out from beneath the roll-up and press the [Cycle-Start] button on the operator station. The [Cycle Start] button press will cause the roll-up door to lower until it reaches a “door closed” position as reported by non-safety rated CAM switches on the motor drive unit. When the door has lowered, the two safety switches on both ends of the door's weighted bar should close. Once both magnetic safety sensors (left side and right side) have been satisfied, the limited speed function is disabled (in the case of the AWC-52 cell, the robot must fully engaged itself into the closed station before the speed limiting function is disabled and the robot can begin unlimited full-speed operation). Assuming there are no faults or issues during the production of the part, once completed the robot should return to a safe position, issues the output to open the roll-up door. Once the robot’s INFORM job issues the output to open the station door, the door will begin its upward motion which will cause the magnetic safety switches to open which will cause the robot to enter limited speed operation again and the headstock positioners on the AWC-50S or 52S cells will then fall back into “Standstill Monitoring”. Once the door has opened completely, the “door up” signal from the motor CAM switch will remove power from the motor contactor. This allows the operator to then walk beneath the roll-up door, remove the completed part, and then load the next part to be processed. Once loaded, the process begins again.

1.2.4.3 Key Safety Devices:

- DX200 controller with MA1440 & FSU (MHT-185 positioners on AWC-50S & AWC52S):
  - Dual channel pendant E-Stop
  - Dual channel pendant “deadman” switch
  - [Teach/Play] mode selector switch
  - Functional Safety Unit (FSU)
    - Responsible for monitoring the roll-up door safety input switches (door closed)
    - Managing which zones the robot can be in based on the roll-up door safety switches
    - Managing when the external axes on the AWC-50S and AWC-52S are in “Standstill Monitoring” based on the roll-up door safety switches.
    - Limiting robot travel speeds based on robot location and roll-up door status

- Safety Gate Interlocks (qty 2)
  - Dual channel dry contact outputs
1 Introduction
1.2 System Overview

- Roll-up door position safety sensors (qty 2 per station, left-side/right-side)
  - Dual channel sensors sensing made when the door is in the closed position
  - Both left-side and right-side safety switches are monitored in series by a Pilz safety relay that drives the FSU input

- Roll-up door (qty 1 per station):
  - 3-phase 208VAC motor without brake. Does have a CAM switch indicating when the door is fully raised or lowered

- Three-phase solid-state motor starter (qty 1 per station)
  - This device is listed as performance level e (but is being used in much lower performance level in this application)

- Three button operator station:
  - Dual channel [Cycle Start] button
  - Dual channel "E-Stop"
  - Single channel “Auto/Manual" switch

1.2.4.4 Safety Logic Implementation (all cells):

- **Teach/Play selector relay (both AWC-50(S) & AWC-52(S))**: It has been stated that disabling the FSU is difficult when the robot violates a zone or corrective action needs to be taken. Disabling the FSU functions requires the “Safety Mode” password to disable individual functions and then all of those functions have to be re-enabled before “Play Mode” production can begin. To eliminate these issues, a “Play/Teach Mode” relay is being implemented to quickly disable and re-enable FSU functions as the controller toggles between “Teach Mode” and “Play Mode”. Implementation of this “Play Mode” relay is achieved by using the “Safety Logic Circuit” to enable GSOUT1 on the Machine Safety board anytime the controller is placed into “PLAY MODE”. GSOUT1 is then connected to two relays (one per channel) and contact monitoring is achieved via a set of normally closed contacts (one from each relay) are tied in series to the EDM monitoring input for GSOUT1. The contacts from the two relays then drive the FSU's FSBIN1 safety inputs notifying the FSU of when the controller is in “PLAY MODE” thereby disabling most of the FSU's monitoring functions.

![Fig. 1-3: Safety Logic Circuit](image-url)
1.2  System Overview

**AWC-50(S) Safety Logic Implementation**

In “Teach Mode”, a “R1 Teach Zone” ensures the robot remains within the confines of the work cell. No additional safeguards are taken do to “Teach Mode” speeds are already limiting speed to 250 mm/sec. With an AWC-50S cell in “Teach Mode”, “Standstill Monitoring” disables S1 so that the programmer can jog the positioners with the roll-up door either up or down.

*Fig. 1-4: AWC-50 Teach Zone*

In “Play Mode”, a combination of the FSU-based “Zone Monitoring”, “Speed Limiting”, and “Standstill Monitoring” (50S only) makes sure the robot is only able to enter “Station1 Zone” when the roll-up door is closed. Otherwise, the robot must remain within the “R1 Play Mode Home” zone behind the table/positioner. Since the “inner-cell” light curtains will NOT detect someone reaching beyond the tooling and contacting the robot while the door is up, the FSU's “Speed Limit” function will limit the robot's speed to 500 mm/sec maximum while in “Play Mode” and the door is up. This will allow the robot to clean its torch and access a tip-change station if needed just at limited speeds. This does not eliminate the hazard of the robot but instead increases avoidance response time, limits severity, and thereby lessen the likelihood. The FSU-based “Standstill monitor” function will be used to ensure that the MHTH-185 headstock remains stationary in “Play Mode” anytime the roll-up door is not down.

*Fig. 1-5(a): AWC-50 Play Mode Home Zone*
**AWC-52(S) Safety Logic Implementation**

In "Teach Mode", the robot remains within the confines of the work cell due to an established "R1 Teach Zone". No additional safeguards are taken do to "Teach Mode" speeds are already limiting speed to 250 mm/sec. With an AWC-50S cell in "Teach Mode", "Standstill Monitoring" disables S1 and S2 so that the programmer can jog the positioners with the roll-up door either up or down.
In “Play Mode”, a combination of FSU-based “Zone Monitoring”, “Speed Limiting” and “Standstill Monitoring” (52S only) will ensure that the robot does not enter the same area where the operator is loading parts. In the case of the AWC-52S cells, the station axis where the operator is working will remain in “Standstill Monitoring” while the roll-up door is up. The robot must remain behind the station where the roll-up door is open and while moving within that zone, the robot will be moving at a maximum speed of 500 cm/min. The robot can travel at 100% maximum speed within the “Robot Safe” zone behind the tables, only if both station's roll-up doors are lowered. External axis station where the roll-up door is not closed enables “Standstill” monitoring.

Fig. 1-7(a): AWC-52 - Play Mode Home Zone

Fig. 1-7(b): AWC-52 - Play Mode Work Station 1
1 Introduction
1.2 System Overview

Fig. 1-7(c): AWC-52 - Play Mode Work Station 2

Fig. 1-7(d): AWC-52 - Play Mode Work Station 1 or 2

Fig. 1-7(e): AWC-52 - S1/S2 Standstill Monitoring
Fig. 1-7(f): AWC-52 - R1 Play Speed Limit (In effect when either station is open)
1.3 Reference Documentation

For additional information, refer to the following:

- Motoman MA1440 Manipulator Manual (P/N 165830-1CD)
- Motoman Brake Release Manual (P/N 165310-1CD)
- Motoman DX200 Controller Manual (P/N 165292-1CD)
- Motoman Maintenance Manual for DX200 (P/N 165293-1CD)
- Motoman Operator's Manual for Arc Welding (P/N 166346-1CD)
- Motoman DX200 Concurrent I/O Manual (P/N 165294-1CD)
- Motoman MH-Series Positioner Manual (P/N 168961-1CD)
- Motoman INFORM User's Manual (P/N 165301-1CD)
- Vendor manuals for system components not manufactured by Motoman

1.3.1 Location of Operations in Reference Documentation

The table below provides the location(s) for various operations within the included reference manuals.

<table>
<thead>
<tr>
<th>Description</th>
<th>Manual/Chapter</th>
<th>Handling</th>
<th>Installation &amp; Commissioning</th>
<th>Start-up</th>
<th>System Information</th>
<th>Use of System</th>
<th>Maintenance</th>
<th>Decommissioning</th>
<th>Emergency Situations</th>
<th>Robot Specific Information</th>
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1.3 Reference Documentation

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<th>Handling</th>
<th>Installation &amp; Commissioning</th>
<th>Start-up</th>
<th>System Information</th>
<th>Use of System Information</th>
<th>Maintenance</th>
<th>Decommissioning</th>
<th>Emergency Situations</th>
<th>Robot Specific Information</th>
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## 1.3 Reference Documentation

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<td>Raising and Lowering Speed Using Pendant</td>
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<td>Robot Suitable for Integrations</td>
<td>Documents Included</td>
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- Checkmark indicates availability.
1.4 Customer Service Information

If you need assistance with any aspect of your ArcWorld® C-50 Series system, please contact Motoman Customer Support at the following 24-hour telephone number:

(937) 847-3200

For routine technical inquiries, you can also contact Motoman Customer Support at the following e-mail address:

technicalsupport@motoman.com

When using e-mail to contact Motoman Customer Support, please provide a detailed description of your issue, along with complete contact information. Please allow approximately 24 to 36 hours for a response to your inquiry.

Please use e-mail for routine inquiries only. If you have an urgent or emergency need for service, replacement parts, or information, you must contact Motoman Customer Support at the telephone number shown above.

Please have the following information ready before you call:

- System: ArcWorld® C-50 Series
- Robots: MA1440
- Positioner: MH-185
- Primary Application: Arc Welding
- Controller: DX200
- Software Version: Access this information on the Programming Pendant’s LCD display screen by selecting {MAIN MENU} - {SYSTEM INFO} - {VERSION}
- Robot Serial Number: Located on the robot data plate
- Robot Sales Order Number: Located on the DX200 controller data plate
2 Equipment Description

2.1 Robot Description

The ArcWorld® C-50 Series system uses the Motoman MA1440 six-axis robot. The MA1440 robot is specifically designed for arc-welding applications. The MA1440 robot has a payload capability of 6 kg and features a horizontal reach of 1440 mm. The MA1440 robot features a relative positioning accuracy of ±0.08 mm.

The MA1440 robot features an internal cabling design that provides high flexibility and streamlines the robot profile, thus allowing access into confined spaces. The robot's B-axis (Pitch/Yaw) features an expanded range of motion that improves circumferential welding on cylindrical work pieces. The T-axis (Twist) can rotate the welding torch ± 200 degrees without cable interference.

The robot's S-axis rotation is physically limited by hard stops located in the base of each robot. For more information, refer to the MA1440 Manipulator Manual that came with your ArcWorld® C-50 Series system documentation package (see section 1.3 “Reference Documentation”).

2.2 DX200 Controller

The DX200 robotic controller (see Fig. 2-8) includes a Windows® CE Programming Pendant with a color touch screen, high-speed processing, built-in Ethernet, and a robust PC architecture. Lower integration costs are available with the Category 3 Functional Safety Unit (FSU). High reliability and energy efficiency Improved maintainability, reduced Mean Time to Repair (MTTR) The DX200 easily handles multiple tasks and can control up to eight robots (up to 72 axes, including robots and external axes) and input/output (I/O) devices. Advanced Robot Motion (ARM) control provides high-performance path accuracy and vibration control.

The DX200 coordinates the operation of the ArcWorld® C-50 Series system. It controls manipulator movement and welding power supply, processes input and output signals, and provides the signals to operate the welding system.

For additional information on the Motoman DX200 controller, please refer to the DX200 Controller Manual that is included with your ArcWorld® C-50 Series documentation package (see section 1.3 “Reference Documentation”).
2.2.1 Programming Pendant

The Programming Pendant (see Fig. 2-9) provides the primary means of programmer/operator interaction with the ArcWorld® C-50 Series system. The pendant features the Windows® CE operating system and displays information on a 6½-inch, color LCD, touch-screen display (640 X 480 VGA). The pendant also incorporates a CompactFlash® card slot for program backups.

The Programming Pendant provides icon-driven system programming. It also features a menu-driven interface to simplify operator interaction with the robots. Most operator controls are located on the Programming Pendant. This allows remote installation of the DX200 controller. By using the Programming Pendant, the operator can teach the robots motion; perform programming, editing, maintenance, and diagnostic functions; and enable or disable Operator Station control of the ArcWorld® C-50 Series system. For detailed information on the pendant’s programming keys, programming functions, and display functions, please refer to the DX200 Operator’s Manual for Arc Welding that is included with your ArcWorld® C-50 Series system documentation package (see section 1.3 ‘Reference Documentation’).
2.2 DX200 Controller

Figure 2-9: Programming Pendant

- The Programming Pendant’s LCD display goes dark after a few minutes of inactivity. Press any key to restore the screen.

- Operator Station Enable or Disable is accomplished with the Programming Pendant’s Mode Select Switch. To transfer control of the ArcWorld® C-50 Series system to the Operator Station, set the Mode Select Switch to REMOTE.
2.3 Operator Station

The Operator Station (see Fig. 2-10) includes a NEMA enclosure that is mounted onto the fence. The following paragraphs describe the Operator Station controls.

Figure 2-10: Operator Station

2.3.1 CYCLE START/CYCLE LATCHED Button

The operation of the CYCLE START/CYCLE LATCHED button is dependent on the structure of the Control Master job. Altering the Control Master job could result in injury to personnel or damage to the equipment.

The green CYCLE START/CYCLE LATCHED button initiates a job cycle when the robot is in HOME position. If the CYCLE START/CYCLE LATCHED button is pressed while the robot is outside HOME position, the Cycle Start command does not execute until the robot returns to HOME position.

The Cycle Latched lamp illuminates when the CYCLE START/CYCLE LATCHED button is pressed during operation. When the lamp is illuminated, the positioner will sweep and the robot will begin to weld immediately after the current job cycle is complete. It is not necessary to wait for the robot to finish welding and return to HOME position before pressing the CYCLE START/CYCLE LATCHED button. Pressing this button while the robot is still in motion latches the Cycle Start command into the controller.

2.3.2 EMERGENCY STOP (E-STOP) Button

Pressing the red EMERGENCY STOP (E-STOP) button removes servo power and stops all system operation. Brakes are applied to the robot, and all positioner motion is stopped.

2.3.3 POSITIONER AUTO/MANUAL

The POSITIONER AUTO/MANUAL switch is used to select automatic or manual mode for the positioner. When the switch is set to the AUTO position, the robots weld the parts immediately after the positioner sweeps. When the switch is set to the MANUAL position, the robots do not immediately start to weld after the positioner sweeps. The robots remain in HOME position.

The POSITIONER AUTO/MANUAL signal depends upon the structure of the Control Master job.
2.4 Work Stations

Each ArcWorld® C-50 Series work cell comes with positioner support posts for weld table or MH-series headstock mounting. Table 2-2 shows the optional weld tables and headstocks available for each work cell. Motoman does not supply weld tables with any standard cell.

Table 2-2: Work Cell Options

<table>
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<th>System</th>
<th>Weld Table Mount</th>
<th>MH-series Headstock</th>
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<td>ArcWorld C-50S</td>
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<td>ArcWorld C-52S</td>
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2.4.1 Stationary Weld Tables

Optional weld tables are available to secure production parts using customer-supplied tooling fixtures. See Table 2-3 for weld table specifications.

Table 2-3: Weld Table Specifications

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<th>Specifications</th>
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<td>Temperature Operating Range</td>
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<td>Humidity</td>
<td>Non-condensing 10 - 90% relative humidity is acceptable (see note below).</td>
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<tr>
<td>Welding Current Rating</td>
<td>600 amperes at 100% duty cycle</td>
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In high humidity areas, the weld table tooling plates may rust or corrode. Use surface protection to prevent corrosion of unpainted tooling surfaces.

2.4.2 MH185 Headstock (ArcWorld C-50S/52S Only)

The Motoman MH185 drive assembly provides precision-controlled rotary motion and can be mounted in any orientation. The standard configuration utilizes an AC servo motor, a high-ratio gear reducer with integral output bearing, faceplate, and a cast iron housing. It also includes dual integral position switches and one or more weld ground brushes rated at 400 amps per brush. One bush is standard. An optional second is available.

For detailed positioner specifications for the MH185 headstock, including a parts lists breakdown, refer to the MH-series Positioner Manual with MotoMount and Drive Assemblies (see section 1.3 “Reference Documentation”).

In high humidity areas, use surface protection to prevent corrosion of the tooling plates.
2.5 Welding Equipment

In its standard configuration, the ArcWorld® C-50 Series system includes a welding power source, wire feeder, torch, and torch mount. Optional equipment — including water circulators, ComArc™ units, and torch tenders — may also be included with your system.

2.5.1 Power Sources

Motoman offers several different power sources for use with the ArcWorld® C-50 Series system, depending on the customer’s specific application. For additional information, refer to the welding power source vendor manual that is included with the ArcWorld® C-50 Series documentation package (see section 1.3).

2.5.2 Wire Feeder

The wire feeder mounts on the robot’s arm. This 4-roll wire feeder provides reliable wire feeding at rates up to 750 inches per minute (ipm). An integral gas valve provides fast gas response time. Interchangeable feed rolls are used to accommodate different types and sizes of wire.

2.5.3 GMAW Torch

The ArcWorld® C-50 Series system uses either an air-cooled or water-cooled robotic/automatic GMAW torch. These are heavy-duty torches designed for quick replacement and a minimum of robot reprogramming. The GMAW torch is installed in a torch mount at the end of the robot’s wrist. The torch mount provides multi-dimensional impact (collision) detection to protect the robot, torch, fixture, positioner, and work piece from damage in the event of a collision. Any torch impact (collision) triggers an Emergency Stop condition (refer to section 4.3.2 and section 4.3.3 “Shock Sensor Recovery”). For applications that use the water-cooled torch, the ArcWorld® C-50 Series system includes a water circulator kit.

2.6 Safety Features

The ArcWorld® C-50 Series system includes a total safety environment. When all standard safety precautions are taken, the safety equipment helps to ensure safe operation of the robotic cell. The ANSI/RIA R15.06-2012 Robot Safety Standard stipulates that the user is responsible for safeguarding.

**NOTE**

Users are responsible for determining whether the provided safeguards are adequate for plant conditions. Users must also ensure that safeguards are maintained in working order.
2.6 Safety Features

2.6.1 Part Loading Door(s)

WARNING

Do not operate this equipment unless the access doors are in place and working properly or eye damage can occur!

The ArcWorld C-50 features one part loading door, while the ArcWorld C-52 features two. These independent, motorized part loading doors provide access to the loading and unloading areas of the work cell. Durable, black armor pleated curtain fiber act as a shield to protect the operator from the arc radiation and sparks produced by the welding operation. Both doors slide in rails and utilize electromagnetic safety interlocks to deny cell access during the welding process. Adjustments to let the doors open or close easier are made using spring detents.

2.6.2 Arc Screens

WARNING

Never look directly at the welding arc without protective eye wear. The welding arc can cause permanent eye damage if viewed without protective shielding or eye wear.

Two types of arc screens are part of the ArcWorld® C-50 Series system:

- The operator doors: These durable, black armor pleated curtains protect the operator by blocking ultraviolet radiation, sparks, and other welding by-products that result from the welding operation.
- Safety fence covering: The orange-colored sheeting that covers the safety fence composes the second arc screen. This material reduces the amount of ultraviolet radiation that escapes the ArcWorld® C-50 Series work cell during welding operations.

2.6.3 Safety Fencing

The heavy-gauge, welded wire safety fencing that is provided with the ArcWorld® C-50 Series system encloses the entire work cell. It forms a physical barrier that prevents personnel from entering the work cell during automatic operation.

2.6.4 EMERGENCY STOP (E-STOP) Buttons

In addition to the safety features described above, the ArcWorld® C-50 Series has strategically placed EMERGENCY STOP (E-STOP) buttons. These are operator-actuated devices that, when activated, immediately stop all system operation. Brakes are applied to the robot, and all servo power is removed from the system. The following is a list of E-STOP locations:

- Programming Pendant
- Operator Station
2.6.5 **ENABLE Switch**

The ENABLE switch is a three-position switch located on the back of the Programming Pendant. It is a safety feature that controls servo power while the pendant is in TEACH mode. When pressed in, this switch enables the operator to turn servo power on. Should the operator release the switch or grasp it too tightly, however, servo power is immediately removed, preventing further robot movement. For detailed information about the operation of the ENABLE switch, refer to the **DX200 Controller Manual** and the **Operator’s Manual for Arc Welding** that came with your system (see section 1.3 “Reference Documentation”).

2.6.6 **Robot Braking System**

The robot brakes are designed to protect the robot and other system components from damage in the event of, for example, a system or robot failure or a loss of drive power. The brake release allows the operator to release the brake of a specific robot axis when drive power has been removed from the system. The Programming Pendant is used to access the brake release function. Refer to the **Brake Release Manual** that came with your system (see section 1.3 “Reference Documentation”).

2.6.7 **Interlocked Work-cell Door**

A safety interlock on each of the ArcWorld® C-50 Series robotic work-cell access doors prevents entry into the work cell during PLAY mode. Opening either work-cell door while the ArcWorld® C-50 Series system is in PLAY mode immediately triggers an E-STOP condition. Brakes are applied to the robot, all servo power is removed, and all positioner motion stops. To continue operation of the ArcWorld® C-50 Series system, the operator must reset these safety interlocks. Refer to section 4.3.2 “Emergency Stop (E-STOP) Recovery” for E-STOP reset procedures.
3 Installation

3.1 Materials Required

The ArcWorld® C-50 Series system can be installed in just a short amount of time. Comply with all the safety instructions and precautions given throughout this manual during the installation process. Failure to use safe work practices can result in damage to equipment and injury to workers.

It is the purchaser’s responsibility to determine and supply all anchoring and foundation requirements for installation. Before installing ArcWorld® C-50 Series cell, refer to chapter 6 "Anchoring" to determine the anchor and foundation requirements for all the equipment used in your cell.

The instructions given in this section are general guidelines for installing the ArcWorld® C-50 Series system. Refer to your system drawings and relevant system component manuals for specific installation information (see section 1.3 “Reference Documentation”).

CAUTION

Installation of the ArcWorld® C-50 Series system is not a task for the novice. The ArcWorld system is not fragile, but it is a highly sophisticated robotic system. Handle components with care. Rough handling can damage the system’s electronic components.

3.1 Materials Required

All system components and most hardware items required for installation of the ArcWorld® C-50 Series system are included with your shipment. There are, however, some required items that the customer must supply, such as typical installation and maintenance tools (refer to section 3.1.2 “Recommended List of Hand Tools and Equipment”) and special anchor bolts (refer to chapter 6 “Anchoring”).

3.1.1 Customer-supplied Items

- Shielding gas for the welding torches
- Local electrical service
- Earth ground wires for the robots, the DX200 controller, and peripheral equipment
- Earth ground rods and/or buried copper sheeting (quantity and placement depth as required to achieve specified resistance-to-ground reading of 100 ohms or less)
- Chemical (optional) to increase the conductivity of soil in the vicinity of the earth ground system
- Welding wire
- Clean, dry air supply (for torch tender or wire cutter options):
  - Flow Rate: 0.425 m³/min. (15 cfm)
  - Pressure: 620 kPa (gage) [90 psi (gage)]
- Forklift(s) and/or overhead crane
- Special anchor bolts and drill bits (refer to chapter 6 “Anchoring” for suggested anchoring hardware)
3.1.2 Recommended List of Hand Tools and Equipment

- Safety glasses
- Face shield
- Gloves (heavy-duty leather recommended)
- Levels (short and long)
- Ratchet handle (with 3/4-inch hex socket)
- Adjustable wrench
- Hammer drill with appropriate concrete bits
- Phillips and flat-blade screwdrivers
- Hammers (dead-blow and steel)
- Hammer (non-marring)
- Socket sets (SAE and metric)
- Air-impact gun (with 3/4-inch hex socket)
- Open-end wrench sets (SAE and metric)
- Allen® wrench sets (SAE and metric)
3.2 Site Preparation

**WARNING**

Be sure to provide sufficient room for access to the work-cell door, Operator Station, and system components that are exterior to the work cell. Failure to observe this precaution could result in injury to personnel during system operation and maintenance.

To prepare your site, proceed as follows:

1. Clear the floor and overhead space needed for the ArcWorld® C-50 Series system (see Fig. 3-1). Allow an additional 1.2 m to 1.5 m on all sides of the work cell to provide the clearances needed for installation.

2. Gather all the customer-supplied items and required tools (refer to section 3-1).

*Figure 3-1: Area Needed for Installation (AWC-52 Shown)*
3.3 Installing the System Base

The ArcWorld® C-50 Series system is shipped complete on a wooden platform. To install the system, refer to your system drawings and proceed as follows:

1. Unbolt the system from the shipping platform. The bolts that secure the system to the wooden platform go down through the hollow leveling screws and are threaded into the wooden shipping platform (see Fig. 3-2). It may be necessary to hold the leveling screws in place with a suitable open-end wrench while removing the shipping bolts.

2. Using a forklift, lift the system base from the wooden shipping platform. Discard or recycle the wooden shipping skid.

3. Place the system base in position (see Fig. 3-1).

CAUTION

Handle system components carefully. Some components can be damaged if dropped or otherwise handled roughly.

WARNING

As shipped, the system base (with equipment) weighs approximately 2050 kg. Use a forklift that is rated for this amount of weight load.

Figure 3-2: Typical Stabilizing Screw and Removal of A Shipping Lag Bolt

NOTE – An air-powered tool is not required for removal of the shipping bolts, as these fasteners can be removed with ordinary hand tools. However, the air-powered tool does make quick work of the task.

NOTE

Make sure that there is adequate room on all sides of the system (see Fig. 3-1).
4. Carefully remove the protective plastic wrapping from the robot, torch, and rotary positioner.

5. Inspect the robot, torch, and rotary positioner for shipping damage.

If you notice any equipment damage, notify your shipping contractor as soon as possible.

6. Use an M36 socket to loosen or tighten each leveling bolt to level the common base (see Fig. 3-2).

**CAUTION**

Be absolutely certain of the correct location for the system base before securing the base with anchor (lag) bolts.

7. Secure the system base to the floor. Use a suitable concrete drill bit and special anchor (lag) bolts (refer to chapter 6 “Anchoring” for the correct drill bit and anchor bolt). Be sure to remove all concrete dust from the drilled hole before driving each anchor bolt.
3.4 Cable Connections

After the ArcWorld® C-50 Series system is anchored in its correct location, connect electrical service according to the system drawings and schematics included in the ArcWorld® C-50 Series system documentation package.

3.4.1 Connection to Local Electrical Service

**WARNING**

Local electrical service connection to the ArcWorld® C-50 Series system must be performed by a qualified, licensed electrician. Electrical and grounding connections must comply with the National Electrical Code (NEC), as well as all local electrical codes.

**NOTE**

The ArcWorld® C-50 Series system is configured for three-phase 460/480V AC primary power. For additional information, refer to the electrical drawings and schematics that are included with your system documentation package (see section 1.3 “Reference Documentation”).

After all the system components have been properly installed and interconnected, connect local electrical service to the DX200 controller and welding power source (refer to section 3.4.1.1 and section 3.4.1.2).

3.4.1.1 DX200 Controller

For detailed electrical service interconnect procedures for the DX200 controller, refer to the DX200 Controller Manual and ArcWorld® C-50 Series system drawings and schematics that are included with your system documentation package (see section 1.3 “Reference Documentation”).

3.4.1.2 Welding Power Sources

Refer to the welding power source documentation and ArcWorld® C-50 Series system drawings and schematics for electrical service connection procedures and diagrams for the welding power sources.
3.5 Safety/Operation Check

Before installing the tooling and fixtures for your application, take a few minutes to perform the following safety/operation check:

1. Check that each station door is closed and door interlock is engaged.
2. Check the security and integrity of all cable connections.
3. Ensure that the work-cell sliding access door is closed and the door interlock is engaged.
4. Verify the correct settings for the welding power sources (refer to the welding power source documentation that is included with your ArcWorld® C-50 Series system).
5. Verify that local electrical service complies with the power requirements for your ArcWorld® C-50 Series system.
6. Verify that local electrical service is correctly wired into the DX200 controller assembly and the welding power sources.

**CAUTION**
The ArcWorld® C-50 Series system is now ready for power-up. Qualified, trained personnel who are familiar with this system should perform the power-up sequence.

7. Set the power ON-OFF switch on the DX200 controller to ON (see Fig. 2-8 “DX200 Controller”).

**NOTE**
An electrical service disconnect box for the DX200 controller shall be supplied (if desired) by the customer. It is not part of the ArcWorld® C-50 Series system shipment.

8. Set the service disconnect boxes for the welding power sources to ON.
9. Set the power ON-OFF switch on the welding power sources to ON.

**WARNING**
Before operating the robots, verify that each E-STOP push button disables servo power when activated (pushed in). Each E-STOP push button must immediately stop robot and positioner movement when activated (pushed in).

10. Check for correct operation of all E-STOP push buttons (refer to section 2.6.4 “EMERGENCY STOP (E-STOP) Buttons”).
3 Installation
3.6 Installation of Tooling and Fixtures

11. Check for correct operation of the system HOLD buttons on the Programming Pendant. Refer to the Operator’s Manual for Arc Welding for more information on the pendant’s HOLD button (see section 1.3 “Reference Documentation”).

12. Check for correct operation of the work-cell access door safety interlock.

13. Remove power from the ArcWorld® C-50 Series system after completion of the safety/operation check.

3.6 Installation of Tooling and Fixtures

Your ArcWorld® C-50 Series system is now ready for installation of tooling and fixtures for your particular application. Personnel who are familiar with the operation of the ArcWorld® C-50 Series system should perform this installation. After tooling installation, test the positioner for correct operation. Refer to the positioner manual for information on how to test that the positioner is operating correctly (see section 1.3 “Reference Documentation”).

- All tooling and fixtures for the positioner shall be supplied by the customer.

**NOTE**

- Motoman recommends application of a corrosion/rust preventive compound to tooling and fixtures located in a high-humidity environment.
This section provides a brief overview of the operating procedures and precautions for your ArcWorld® C-50 Series system. For more detailed operating information, refer to the specific component manuals that are part of the ArcWorld® C-50 Series system documentation package (see section 1.3 “Reference Documentation”).

The ArcWorld C-50 system is a single station welding cell that uses a Motoman MA-Series robot to weld parts. When the robot completes the welding process, it returns to HOME (Safe) position. The operator then unloads the welded parts and loads new parts for processing. Once the new parts have been loaded and the door closed, the operator can initiate another cycle from the Operator Station.

The ArcWorld C-52 is a two station welding cell. The ArcWorld C-52 uses a Motoman MA-Series robot to weld parts on one station while the operator loads the other station with parts. When the robot completes the welding process, it returns to the HOME (Safe) position. The operator can then initiate another cycle from the Operator Station. This moves the robot to the next station, where the robot then moves from the HOME (Safe) position to complete another welding cycle.

**NOTE**
The customer shall supply all tooling fixtures for the positioner.

### 4.1 Programming

The operation of this system is programming dependent. The following operating instructions are based on one possible configuration of this system. Your system configuration and job structure may differ slightly from that presented here; however, basic operation will be the same. For additional programming procedures and information, refer to the DX200 controller documentation that is included with your ArcWorld® C-50 Series system documentation package (see section 1.3 “Reference Documentation”).

Any changes made to your system configuration and/or job structure will alter the operation of the system. Motoman recommends that you do not modify the original jobs and system configuration of your ArcWorld® C-50 Series system. If you determine a need to modify the original jobs and system configuration, make any modifications to a copy of the original. Keep the original as a backup. Do not modify the original. Modifications must be performed by trained and experienced personnel who are familiar with the operation of the ArcWorld® C-50 Series system. If you have questions concerning the configuration of your system, please contact Motoman’s 24-hour Customer Support (refer to section 1.4 “Customer Service Information”).
4.2 Daily Operation

The procedures below represent the typical operating sequence from power-up to shutdown. Your basic operating procedures may vary depending on your situation.

- Perform the start-up procedure (see section 4.2.1).
- Move the robot to HOME position (see section 4.2.2).
- Start the Control Master job (see section 4.2.3).
- Perform the operation cycle (see section 4.2.4).
- Perform the shutdown procedure (see section 4.2.5).

**NOTE**

Control of the positioner uses collaborative motion between the robot and the positioner external axis.

Collaborative motion is active when jogging the tooling axis, loading, or unloading parts.

4.2.1 Start-up Procedure

To start up the ArcWorld® C-50 Series work cell from a power-off condition, proceed as follows:

1. If installed, switch the DX200 controller electrical service disconnect box to ON.

**NOTE**

An electrical service disconnect box for the DX200 controller shall be supplied (if desired) by the customer. It is not part of the ArcWorld® C-50 Series system shipment.

2. Set the power ON-OFF switch on the DX200 controller to ON.
3. Switch the welding power source electrical service disconnect box to ON.
4. Set the power ON-OFF switch on the welding power source to ON (the ON-OFF indicator lamp on each welding power source illuminates).
5. Open the regulator valve for the welding gas supply.
6. Make sure that the work-cell doors are closed and operating properly and safety interlocks are engaged.
7. Make sure all E-STOP buttons are released. E-STOP buttons are installed at the following locations:
   - Programming Pendant
   - Operator Station
8. Select TEACH mode on the Programming Pendant.
9. Place the robot in HOME position (see section 4.2.2).
4.2 Daily Operation

### 4.2.2 Robot HOME Position

To move the robot to HOME position:

1. Select TEACH mode on the Programming Pendant.
2. Select MAIN MENU on the Programming Pendant's touch screen.
5. Using the cursor keys on the pendant, move the cursor to SAFE job and then press SELECT. The job appears on display screen.
6. Turn servo power on by pressing the SERVO ON button on the Programming Pendant and holding in the ENABLE switch.
7. Use the FWD button on the Programming Pendant to move the robot to HOME position.

### 4.2.3 Master Job

With the system powered up and in TEACH mode, call up the Master job:

1. Select JOB on the Programming Pendant's touch screen.
2. Select CTRL MASTER on the Programming Pendant's touch screen.
3. Press SELECT twice to activate the Master job.
4. Select PLAY mode on the Programming Pendant (job playback operation is enabled).
5. Press the SERVO ON button on the Programming Pendant.
6. Press the START button on the Programming Pendant (the Control Master job cycles, waiting for a Cycle Start input from the Operator Station).

The ArcWorld® C-50 Series work cell is now ready for operation.
4.2 Daily Operation

4.2.4 Operation Cycle

The following is the typical sequence of operation for the ArcWorld C-52 work cell after start-up:

1. Load the fixture with parts to be welded.
2. Close the access door.
3. Press the CYCLE START/CYCLE LATCHED button on the Operator Station. The robot begins the job sequence.
4. While the robot is welding at Station 1, Load Station 2 with parts to be welded.
5. After the parts are loaded, press the CYCLE START/CYCLE LATCHED button on the Operator station; the Cycle Latched light comes on. When the robot has finished welding at Station 1, it returns to HOME position, then proceeds to Station 2.
6. Unload the welded parts from Station 1.

4.2.5 Shutdown Procedure

Use the following procedure to perform a normal shutdown of the ArcWorld® C-50 Series system:

1. Make sure that the robot is in HOME position.
2. Turn off servo power by pressing the E-STOP button on the Operator Station or Programming Pendant.
3. Select TEACH mode on the Programming Pendant.
4. Set the DX200 controller power ON-OFF switch to the OFF position.
5. Set the main power switch on the welding power source to the OFF position.
6. Close the regulator valve for the welding gas supply.
7. Switch the DX200 controller disconnect box (if installed) to OFF.
8. Switch the welding power source disconnect box to OFF.

An electrical service disconnect box for the DX200 controller shall be supplied (if desired) by the customer. It is not part of the ArcWorld® C-50 Series system shipment.

The ArcWorld® C-50 Series cell is now shut down.
4.3 **System Recovery**

When a system error or alarm occurs, you must clear the error or alarm to return the system to normal operation. The paragraphs below describe the different types of alarms and errors you might encounter and how to remedy them when you do.

4.3.1 **Alarms and Errors**

There are three levels of alarms and errors that will stop the program:

- Error messages
- Minor alarms
- Major alarms

For more detailed information on alarm and error recovery, refer to the maintenance and DX200 controller documentation that is included with your ArcWorld® C-50 Series system (refer to section 1.3 “Reference Documentation”).

4.3.1.1 **Error Messages**

Error messages are usually the result of simple, easily cleared operation errors. One example of this type of error is pressing the START button when the robots are not in PLAY mode.

Clear errors of this type by pressing the CANCEL button on the Programming Pendant.

4.3.1.2 **Minor Alarms**

Minor alarms usually involve programming errors. Clear alarms of this type by pressing the CANCEL button on the Programming Pendant.

4.3.1.3 **Major Alarms**

Major alarms usually involve hardware failures. Examples of this type of error include an overload condition and abnormal speed.

Clear alarms of this type by cycling the DX200 controller in accordance with the following steps:

1. Rotate the DX200 controller’s power ON-OFF switch to OFF.
2. Allow the controller’s power ON-OFF switch to remain in the OFF position for approximately 10 seconds.
3. Rotate the controller’s power ON-OFF switch to ON.
4.3 System Recovery

4.3.2 Emergency Stop (E-STOP) Recovery

An Emergency Stop (E-STOP) can occur under any of the following conditions:

- Pressing the E-STOP button on the Operator Station, Programming Pendant, or controller door.
- Opening the access door when the robot is not in TEACH mode.
- Actuating the shock sensor on the torch mount.

After an E-STOP condition occurs, restart the ArcWorld® C-50 Series system as follows:

1. To clear the E-STOP condition, perform any of the following actions that apply:
   - Release the activated E-STOP push button
   - Close the work-cell access door
   - Clear the shock sensor condition (refer to section 4.3.3).

2. Press the SERVO ON button on the Programming Pendant.
3. Press the green START button on the Operator Station.

The ArcWorld® C-50 Series work cell is now ready to continue operation.

4.3.3 Shock Sensor Recovery

The ArcWorld® C-50 Series welding package includes a Motoman gun mount. This mount is designed to protect the torch from damage in case of a crash. A slight deflection of the torch activates a SHOCK SENSOR message that triggers an E-STOP condition. To clear the E-STOP condition, you must override the shock sensor and move the robot clear of the impact. To override the shock sensor, proceed as follows:

1. Select MAIN MENU on the Programming Pendant's touch screen.
2. Select ROBOT on the Programming Pendant's touch screen.
4. Select RELEASE to release the shock sensor.
5. Turn servo power ON (press in on the pendant's ENABLE switch while pressing SERVO ON READY).
6. Move the robot clear of the impact position.

The ArcWorld® C-50 Series cell is now ready to continue operation.
5 Maintenance

Maintenance must be performed by authorized personnel who are familiar with the ArcWorld® C-50 Series system. Be sure to read and understand the documentation for a particular component before doing repair maintenance or preventive maintenance on that component. Be sure that you understand the maintenance procedures, have the proper tools at hand, and comply with all the safety instructions and precautions given throughout this manual.

The maintenance intervals given in Table 5-1 are recommendations only. Adjust the frequency and level of repair maintenance and preventive maintenance to suit your specific equipment schedules and shop environment.

For periodic maintenance procedures and schedules for the individual components of your ArcWorld® C-50 Series system, refer to the documentation that is included with your system documentation package (refer to section 1.3 “Reference Documentation”).

CAUTION

If your system uses water-cooled torches, use only Motoman-specified antifreeze. Typical automotive antifreeze contains additives that can clog the small cooling ports in the torches and damage sealing gaskets in the water circulator pumps.

Table 5-1: Periodic Maintenance

<table>
<thead>
<tr>
<th>FREQUENCY</th>
<th>COMPONENT</th>
<th>PROCEDURE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Daily (or on condition)</td>
<td>Water Circulators (water-cooled torch application only)</td>
<td>Add a mixture of Motoman antifreeze (P/N 131224-1) and distilled water, as required. Mix antifreeze and distilled water in proportions shown on the antifreeze container.</td>
</tr>
<tr>
<td></td>
<td>All safeguard items – work-cell door interlocks, E-STOP push buttons, safety light curtains, arc curtains, etc.</td>
<td>Check the physical condition of the safeguard item and ensure that it is working correctly.</td>
</tr>
<tr>
<td>One Month (or on condition)</td>
<td>ArcWorld® C-50 Series Work Cell</td>
<td>Remove accumulated dirt, grease, and debris from inside and outside the work cell.</td>
</tr>
</tbody>
</table>
6 Anchoring

The purchaser must determine all anchoring and foundation requirements and supply the appropriate anchoring hardware for a particular installation. Always use chemical anchors for equipment with dynamic loads. Use appropriate sized anchors, relative to the clearance holes, to anchor equipment to the floor. Table 6-1 provides sample anchor and foundation requirements for peripheral equipment. Refer to equipment manuals included with your system documentation package (section 1.3 “Reference Documentation”) for anchoring requirements.

![WARNING]

Do not mount robots directly to the floor without the indicated floor plate. Failure to follow floor-plate requirements can result in equipment damage or injury to personnel.

Table 6-1: Minimum Recommended Equipment Anchor Requirements

<table>
<thead>
<tr>
<th>EQUIPMENT</th>
<th>MINIMUM HILTI® ANCHOR ROD DIAMETER/TYPE</th>
<th>MINIMUM FLOOR-PLATE REQUIREMENTS</th>
<th>MINIMUM FOUNDATION REQUIREMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROBOTS</td>
<td>Refer to the manipulator manual included with your system documentation package (section 1.3 “Reference Documentation”) for anchoring requirements. Always use chemical anchors for equipment with dynamic loads. Use appropriate sized anchors, relative to the clearance holes, to anchor equipment to the floor.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>POSITIONER</td>
<td>Refer to the positioner manual included with your system documentation package (section 1.3 “Reference Documentation”) for anchoring requirements. Always use chemical anchors for equipment with dynamic loads. Use appropriate sized anchors, relative to the clearance holes, to anchor equipment to the floor.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PERIPHERAL EQUIPMENT</td>
<td>1/2-inch Kwik Bolt II Style Anchor (Note 1)</td>
<td>Not Applicable</td>
<td>3-inch minimum thickness or 1.3 embedment depth (whichever is larger) 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>WORK-CELL FENCE POSTS</td>
<td>3/8-inch Kwik Bolt II Style Anchor (Note 1)</td>
<td>Not Applicable</td>
<td>3-inch minimum thickness or 1.3 embedment depth (whichever is larger) 4000 psi Reinforced Concrete</td>
</tr>
<tr>
<td>OPERATOR STATION PEDESTAL</td>
<td>1/4-inch Kwik Bolt II Style Anchor (Note 1)</td>
<td>Not Applicable</td>
<td>3-inch minimum thickness or 1.3 embedment depth (whichever is larger) 4000 psi Reinforced Concrete</td>
</tr>
</tbody>
</table>

NOTES:
(1) Reference source: Hilti® Product Technical Guide (section 4.3.3) for hardware specifications or equivalent.

Refer to http://us.hilti.com or http://ca.hilti.com for further information.
Appendix A  Checklist

Since our customer is very important to us we include a checklist to use before start-ups and after maintenance for your convenience and safety.

### BEFORE APPLYING POWER
(Refer to System Drawings)

<table>
<thead>
<tr>
<th>Time/Date</th>
<th>Checked By</th>
</tr>
</thead>
<tbody>
<tr>
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</tr>
</tbody>
</table>

- **Check Mounting**  
  (Refer to Installation Section in all Manuals)

- **Check Power**  
  (Refer to Connections, Controller Manual)

- **Check Ground**  
  (Refer to Grounding in all Manuals)

- **Check Water**  
  (Refer to Operation and Vendor Manuals)

- **Check Air**  
  (Refer to Manipulator and Vendor Manuals)

- **Check Gas**  
  (Refer Operation and Vendor Manuals)

- **Check Interlocks**  
  (Refer to Work Cells in all Manuals)

- **Check Limiting Devices**  
  (Refer to Limits in all Manuals)

- **Check Environment**  
  (Refer to Installation in Controller Manual)

- **Check Version**  
  (Refer to Confirmation of Software Version)

### Other Items to Check Before Applying Power
(Vendor or Integrator Supplied)

<table>
<thead>
<tr>
<th>Time/Date</th>
<th>Checked By</th>
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</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>
## AFTER APPLYING POWER

<table>
<thead>
<tr>
<th>Control Switches</th>
<th>Time/Date</th>
<th>Checked By</th>
</tr>
</thead>
<tbody>
<tr>
<td>Check Axis Move and are Restricted</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(Refer to Basic Specifications, Manipulator Manual)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Check Emergency Stop(s)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(Refer to E-Stop in all Manuals)</td>
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<td>Check External Power Disconnect</td>
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<td>(Refer to Turning OFF The Power Supply)</td>
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<td>Check Teach Mode</td>
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<td>(Refer to Teach Mode, Controller Manual)</td>
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<tr>
<td>Check Playback Mode</td>
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<td>(Refer to Play Mode, Controller Manual)</td>
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<tr>
<td>Check Environment</td>
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<td>(Refer to Location in Manipulator Manual)</td>
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<tr>
<td>Check Safeguards</td>
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<tr>
<td>Check Manual Mode</td>
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<td>(Refer to Manual Mode in Operations Manual)</td>
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<tr>
<td>Check Automatic Mode</td>
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<td>(Refer to Automatic Mode in Operations Manual)</td>
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### Other Items to Check After Applying Power

(Vendor or Integrator Supplied)
### Appendix A Checklist

#### DOCUMENTATION INCLUDED

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<thead>
<tr>
<th>Item</th>
<th>Time/Date</th>
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<tr>
<td>System Drawings</td>
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<tr>
<td>Modifications Made to Original Protective Equipment</td>
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<tr>
<td>End Effector Load Analysis</td>
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<tr>
<td>Instructions on Synchronized Motion</td>
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<td>Programmed Limits</td>
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<td>Collaborative Operation Declaration</td>
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<td><em>(Robot is suitable for integration that includes)</em></td>
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<td>Compliance Documents</td>
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<td><em>(ANSI, ISO, RIA, etc.)</em></td>
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<td>Risk Assessment</td>
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<td><strong>Other Documents to Include</strong> <em>(Vendor or Integrator Supplied)</em></td>
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<td><em>(Vendor Manuals, Supplier Certifications, Compliance)</em></td>
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## MARKINGS INCLUDED ON EQUIPMENT

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<td>Explosive Proof</td>
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<tr>
<td><strong>Order Number (Serial Number)</strong></td>
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### Other Markings on Equipment

(Vendor Machine Designation, Type, Serial No, Version, etc.)

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## OTHER ITEMS

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ArcWorld® C-50 Series
SYSTEM MANUAL

Specifications are subject to change without notice
for ongoing product modifications and improvements.